#### ICA Tutorial on Generalisation & Multiple Representation 2 July 2011 Paris

# Lecture 6 : Multi-agents within automated generalisation (30 mins)

#### Cécile Duchêne COGIT Laboratory – IGN France

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The content of this presentation is partly based on a paper –under submission– written with G. Touya, J. Gaffuri, P. Taillandier, A. Ruas and J. Renard



# Outline

### Multi-agent systems

Why to use agent modelling for generalisation?
 Principles of agent modeling for generalisation
 Overview of existing agent-based generalisation models



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# Multi-agent systems

### Agent: an entity

Guided by a goal to reach

[Weiss 1999]

- Situated in some environment
- Having capacities of perception, deliberation, action, communication
- ≈ object + expert system

# Wulti-agent system: system composed of several interacting agents

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#### **Multi-agent systems: applications**

- Simulation of complex phenomena
  - Ant colonies, human cells, town development, pedestrian moves...
- Complex problem solving
  - Among which constraint-based problems
- 😼 General idea:

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- Each agent is rather simply modelled
  - Perceives a part of the « world », a part of the problem
  - Simple behaviour / knows a part of the solution



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# Outline

# Multi-agent systems

# Why to use agent modelling for generalisation?

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# Giving autonomy to objects

- Generalisation =
  - complex problem
  - distributed over the map space
  - local, context dependent decisions to make
  - => good candidate for multi-agent approaches
- 🎸 1990s
  - Multi-agent paradigm growing
    - Step by step, local approach uses OO + expert systems
  - => agents = natural evolution of this approach

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### Step by step, local approach

 Objects progressively transformed by
 [Brassel & Weibel 1988; McMaster & Shea 1988]
 Algorithms chosen locally

according to conflicts

Specifications
 [Beard 1991] represented as constraints

Operate at different levels; cycles [Ruas & Plazanet 1996]



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#### Who are the agents in generalisation?

Sroups of objects

**V**Objects

- を Parts of objects 🛛 🔿
- The points of the objects
- ...depending on the models
- => The geographic information « generalises itself » (Ruas 1999)

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# Outline

### Multi-agent systems

- Why to use agent modelling for generalisation?
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# The model of [Baeijs 1998]

- Agents = points of the objects; groups of agents
- Known agents = others of the group
- Constraints translated as forces
- Actions = small displacements
- Life-cycle = compute forces, compute displacement, apply displacement



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#### The model of [Baeijs 1998] - results





Before

After

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# The AGENT model [Ruas 1999]



- Actions: generalisation algorithms
- Communication: hierarchical

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#### **Building constraints:**

P <sub>2</sub> ]			
ırea"	GRANULARITY	SQUARENESS	CONCAVITY
2mm² rong	importance: strong priority: satisfaction: advice:	importance: medium priority: satisfaction: advice:	importance: medium priority: satisfaction: advice:

SIZE measure name: "area" current value: goal value: 0.2mm importance: strong priority: satisfaction: advice:

Characterise and Evaluate

#### **Building constraints:**

$J \mathcal{M} = J_{1} (X) + J (X) \mathcal{M}_{2} (\mathcal{M}_{2})$			
SIZE	GRANULARITY	SQUARENESS	CONCAVITY
current value: 0.12mm <sup>2</sup>			
goal value: 0.2mm² 丿			
importance: strong	importance: strong	importance: medium	importance: medium
priority: <b>strong</b>	priority: medium	priority: <b>low</b>	priority: -
satisfaction: low	satisfaction: low	satisfaction: low	satisfaction: perfect
advice:	advice:	advice:	advice:



#### **Building constraints:**

square

rectangle rectangle

$J = \mathcal{S}$ $J = \mathcal{S}$ $J = \mathcal{S}$ $\mathcal{S}$ $\mathcal{S}$ $\mathcal{S}$			
SIZE	GRANULARITY	SQUARENESS	CONCAVITY
measure name: "area"			
current value: 0.12mm <sup>2</sup>			
goal value: 0.2mm <sup>2</sup>			
importance: strong	importance: strong	importance: medium	importance: medium
priority: strong	priority: medium	priority: low	priority: -
satisfaction: low	satisfaction: low	satisfaction: low	satisfaction: perfect
advice: enlarge, enlarge to rectance	advice: simplify to	advice: square	advice: -



#### **Building constraints:**

sguare

enlarge to simplify to

rectangle rectangle

$I = \{0, 1, 1, 2, \dots, 7, N_n \in \mathbb{R}_n\}$	-		
SIZE	GRANULARITY	SQUARENESS	CONCAVITY
current value: 0.12mm <sup>2</sup>			
goal value: 0.2mm <sup>2</sup>			
importance: strong	importance: strong	importance: medium	importance: medium
priority: strong	priority: medium	priority: low	priority: -
satisfaction: low	satisfaction: low	satisfaction: low	satisfaction: perfect
advice: enlarge, enlarge to rectang	advice: simplify to rectangle	advice: square	advice: -





# The AGENT project [Barrault et al. 2001]

#### Vates: December 1997-December 2000

#### Project partners:

- IGN France
- University of Edinburgh
- University of Zürich
- Polytechnical University of Grenoble
- 1Spatial (formerly Laser-Scan)

#### Used and refined the AGENT model

- New implementation
- Rich prototype with lots of generalisation algorithms
- Improvement of life-cycle [Regnauld 2001]
- Application to urban space and roads intensive testings

#### > AGENT model well adapted for hierarchical data

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# The AGENT project [Barrault et al. 2001] results

#### **Urban space**

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Data: IGN France



#### Adaptatations and uses of the AGENT model

- Application to categorical data [Galanda 2003]
- Defines agents and algorithms suitable for land cover generalisation
- Among actions, a snakes based algorithm
  - => step by step and continuous generalisation combined





Data: SwissTopo

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#### Adaptatations and uses of the AGENT model

- Industrialisation
- In the Clarity software (1Spatial)
- By customising Clarity in European NMAs:
  - IGN-France,
    - OSGB,

- Demos this afternoon

- NMAs of German Länder,
- KMS-Danemark

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#### Adaptatations and uses of the AGENT model

#### Industrialisation at IGN-France [Lecordix et al. 2005]





Top100 DB

#### **BD** Carto

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### The CartACom model [Duchêne 2004]

- Target data: low density, no obvious hierarchy
- Agents: only single objects (micro agents)
- Constraints: shared by two agents (relational c.)
- Known agents: neighbours sharing constraints
- Actions: generalisation algorithms, including displacement away from the neighbours
- Communication: each agent
  - $\frac{1}{7}$  informs the others of its own modifications
  - can ask the others to perform actions

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# The model of [Jabeur 2006]

## 🕹 Agents:

- ~micro, meso + layers
- Have a priority depending on the user's interest
- Constraints: size and proximity
- Known agents: neighbours, container/contained
- Actions: scaling, aggregation, displacement, removal
- Communication: ask for action, ask meso for help



#### The model of [Jabeur 2006] - results

Has been applied to on-the-fly generalisation with small scale changes



[Jabeur 2006, p. 206]

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# The GAEL model [Gaffuri 2008]

- Agents: micro/meso + fields decomposed into points (TIN)
- Constraints:
  - object/field + internal to field
  - translated into forces on points
- Known agents: sharing constraints + neighbouring points
- Actions: small displacements (points)
- Communications: ask for action; trigger
  - neighbours

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#### The GAEL model [Gaffuri 2008] – results

#### Scale 1:50 000



**INITIAL STATE** 



AFTER BUILDINGS GENERALISATION



AFTER GAEL



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### The CollaGen model [Touya 2011]

#### **Collagen** = Collaborative Generalisation





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# Conclusions

- Agent approaches: a distributed vision of generalisation
  - Geo agents know/interact with a part of the space (and other agents)
  - Their constraints are assessed locally
    - Close the OO modelling => « easy to think »
  - . but behaviours/knowledge can still be generic
  - shared by types of agents, customised by specialisation

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# Conclusions

Component-based => tolerant to local faults
 Dependent on component quality (algos...)
 Can embed other models

Well suited for cases where decisions should vary locally according to spatial context

### Wain disadvantage: complex to parameterise



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