A Simulated Annealing Algorithm For Cartographic Map Generalization With Multiple Operators

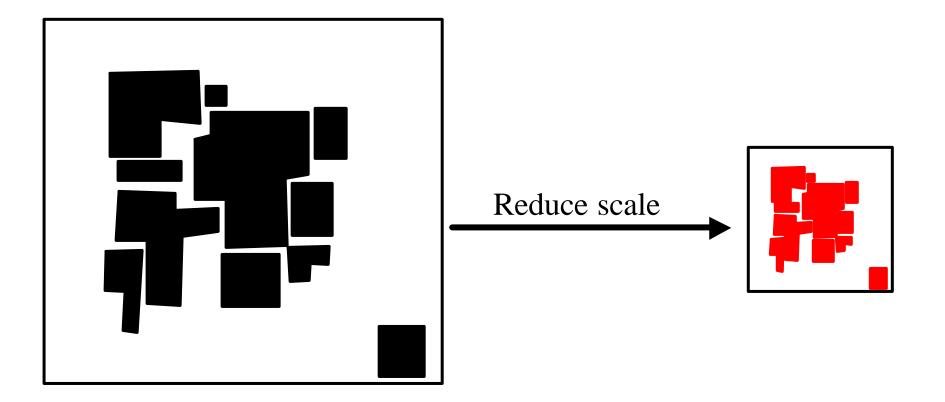
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Ordnance Survey

THE PROBLEM



spatial conflict due to

– objects lying too close to each other

MAP GENERALIZATION - THE SOLUTION

•simplification

•amalgamation

•reduction

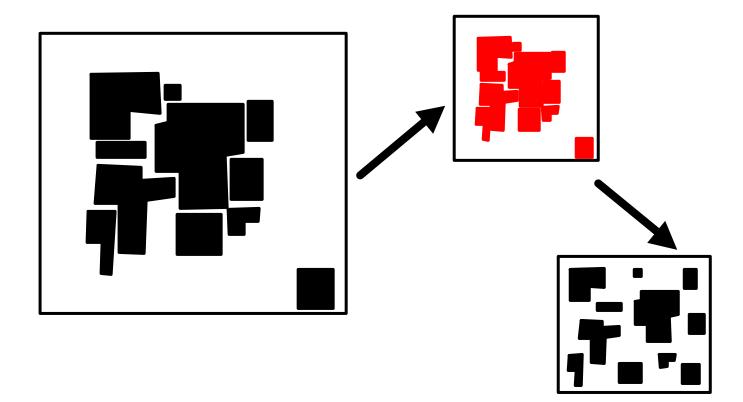
•typification

•deletion

•displacement

•resize

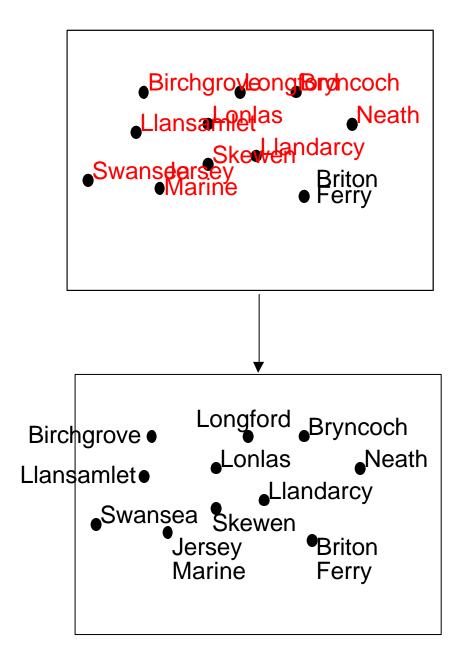
CONFLICT RESOLUTION BY OBJECT DISPLACEMENT

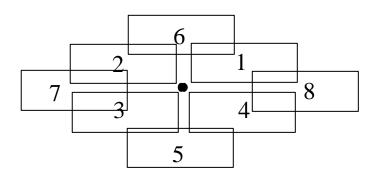


resolve by displacing one or more objects (assume it is permissible to move each object up to a predefined maximum distance from its origin)

OBJECT DISPLACEMENT USING TRIAL POSITIONS

Point Feature Label Placement Using Trial Positions

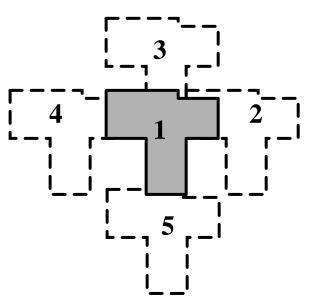




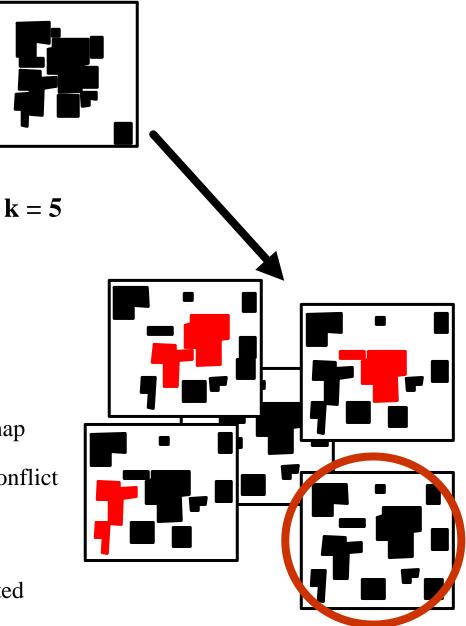
Apply PFLP trial position techniques to Object Displacement

• we have map, n objects, containing conflict

• assign each object k trial positions



- $\ensuremath{\cdot}$ there will be k^n alternative realisations of the map
- hopefully some will contain reduced levels of conflict
- too many to generate and test all
 (e.g. k=8, n =10, > 1 billion configurations)
 -need some strategy for limiting number tested

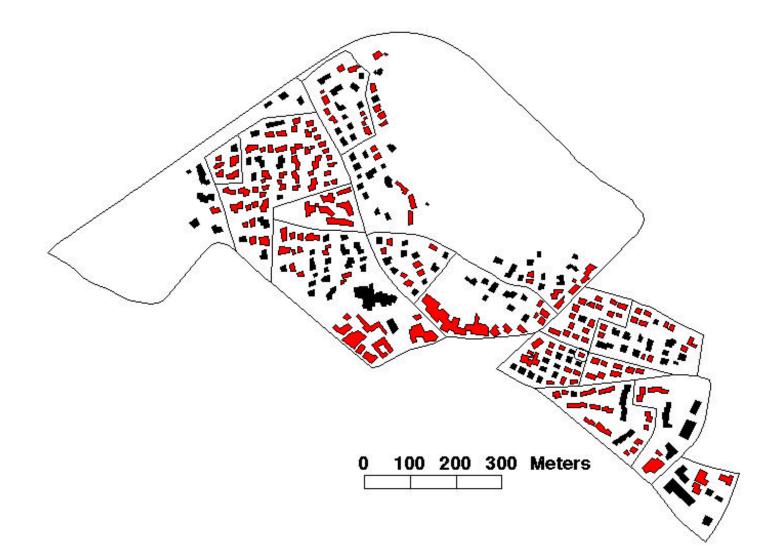


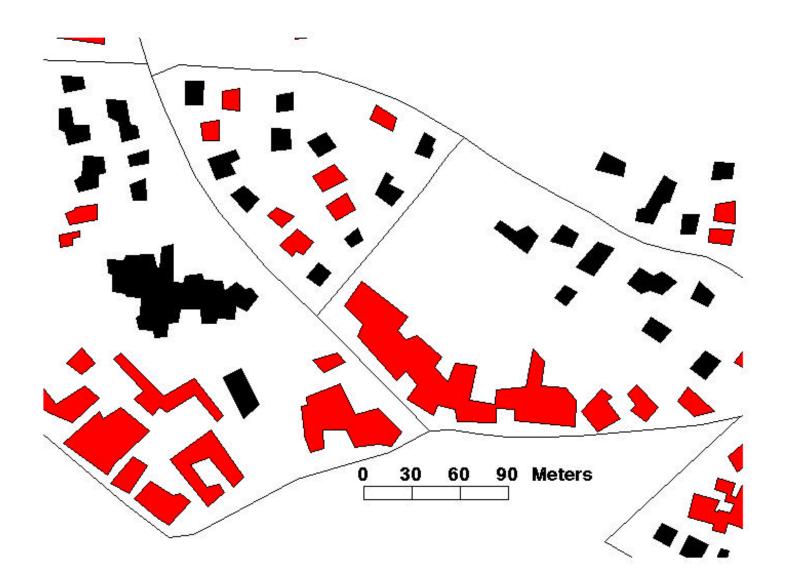
A SIMULATED ANNEALING APPROACH

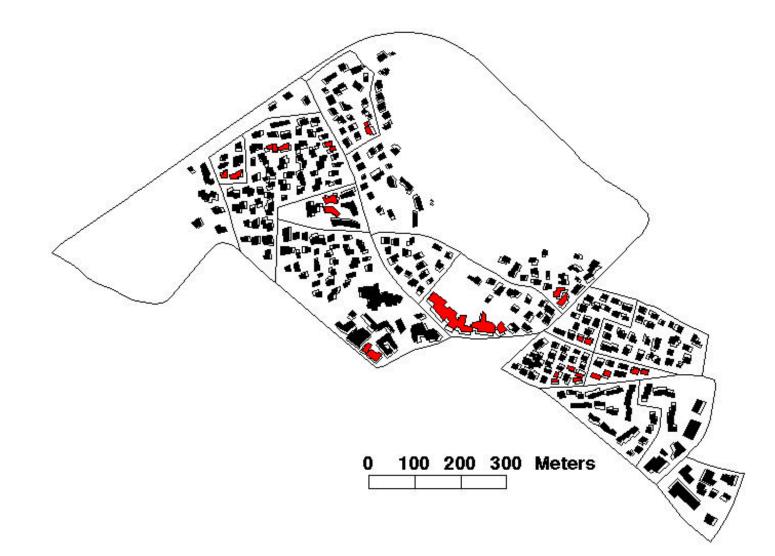
function SimulatedAnnealing

```
input: D<sub>initial</sub>, Schedule, Stop_Conditions
```

```
D_{current} \leftarrow D_{initial}
T←initialT(Schedule)
while NotMet(StopConditions)
     D_{new} \leftarrow RandomSuccessor(D_{current})
      \Delta E \leftarrow C(D_{current}) - C(D_{new})
     if \Delta E >0 then D_{current} \leftarrow D_{new}
      else
           P = e^{-\Delta E/T}
           R=Random(0,1)
           if (R<P) then D_{current} \leftarrow D_{new}
      end
     T←UpdateT(Schedule)
end
Return(D<sub>current</sub>)
```

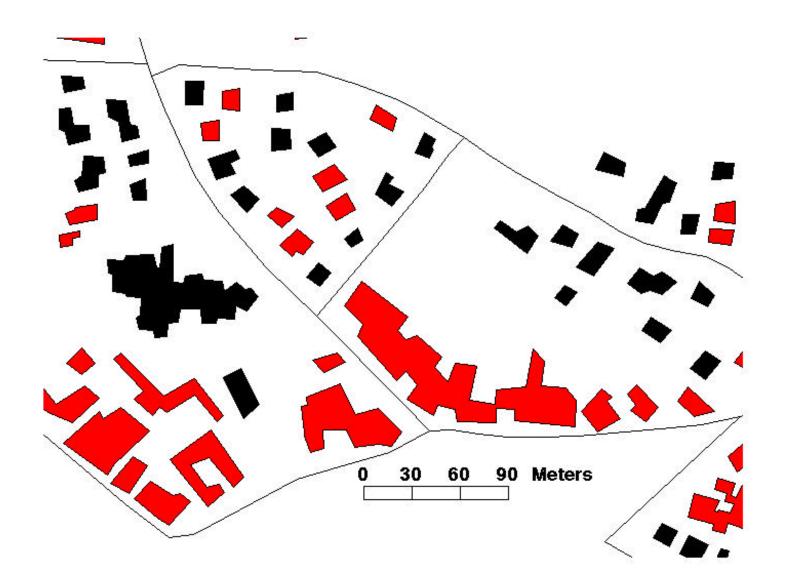




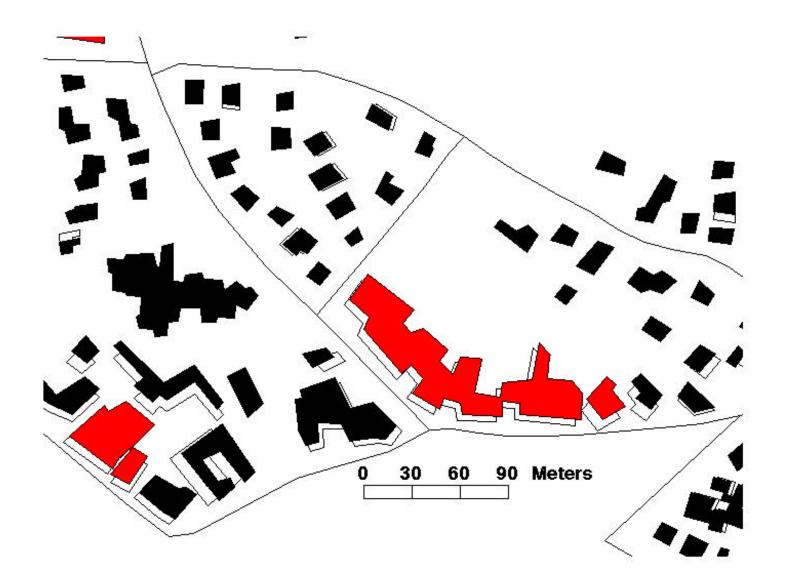




DISPLACEMENT COST

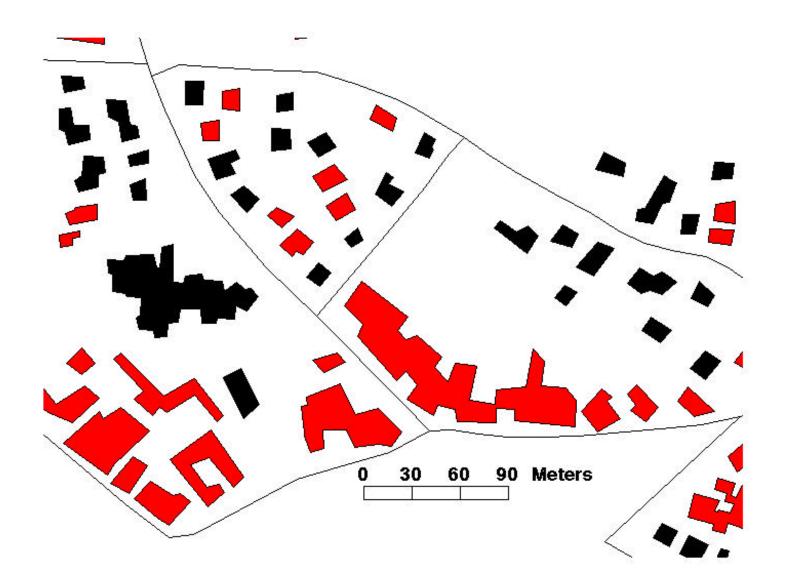






ADDITIONAL OPERATORS

DELETION



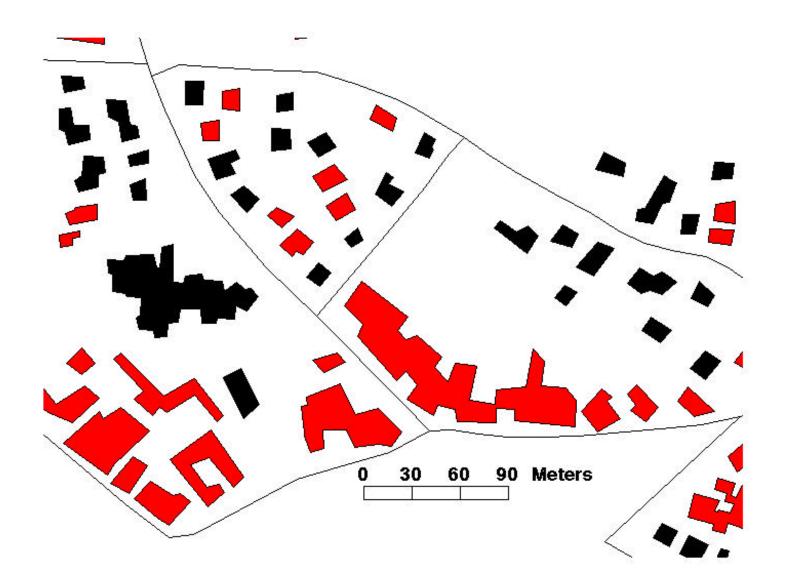


IMPORTANCE WEIGHTING



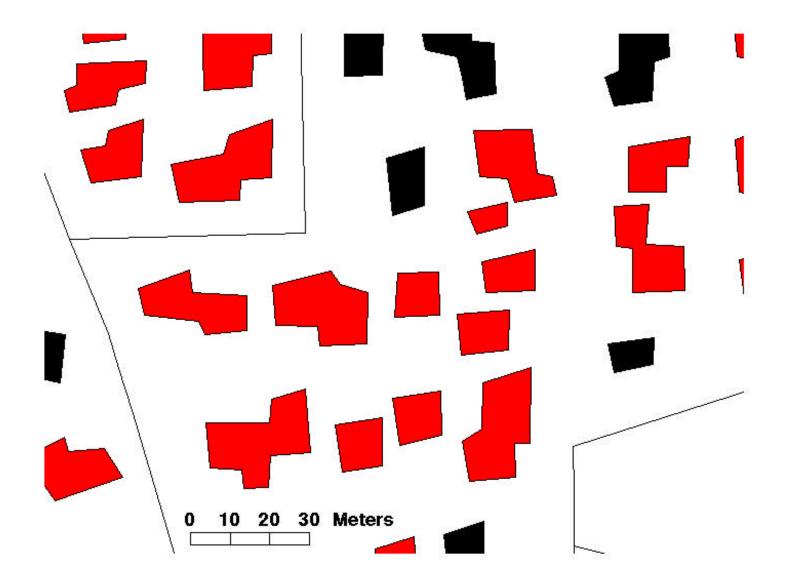


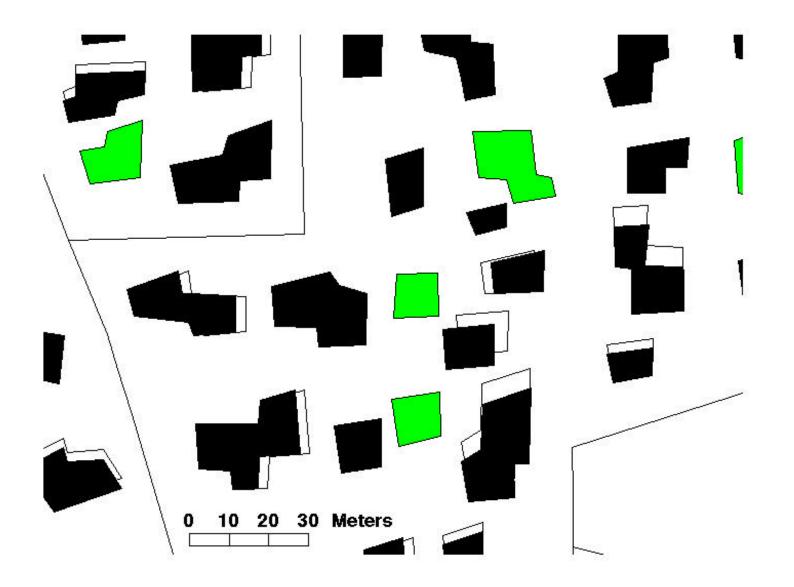
SCALE/RESIZE

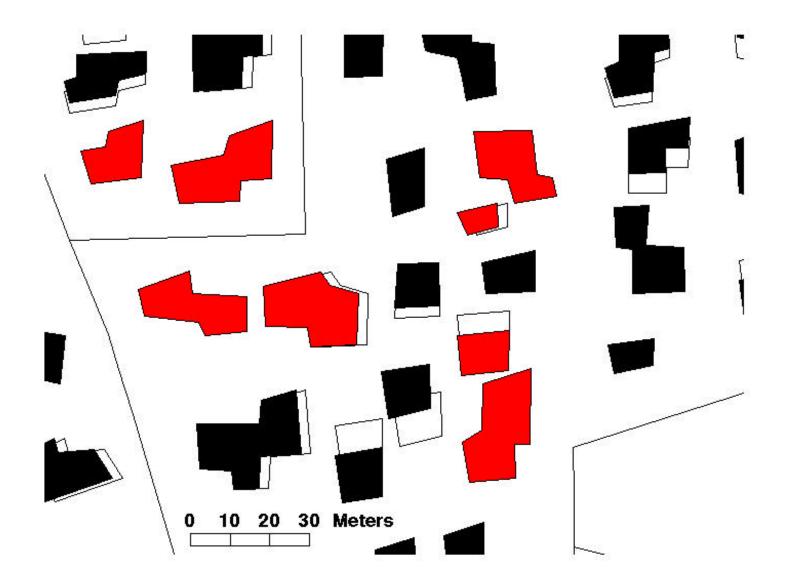


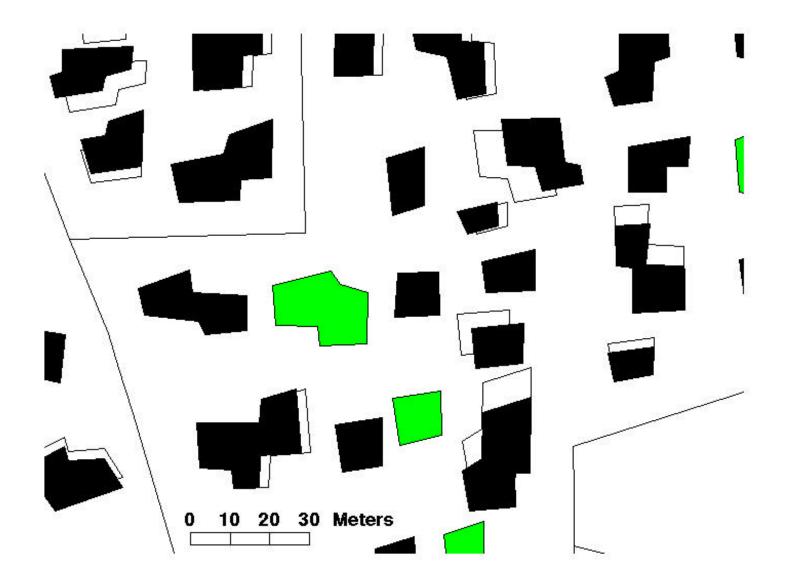


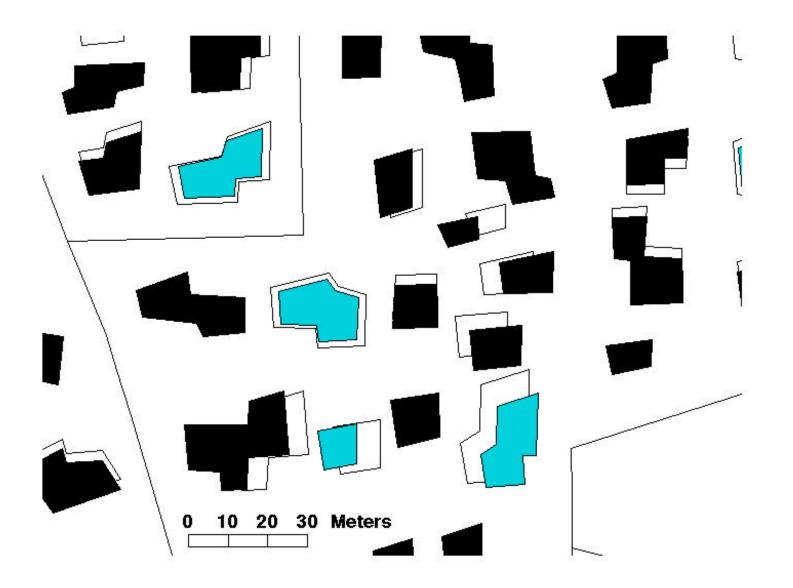
COST SETTING











CURRENT AND FUTURE WORK

•Additional operators e.g. amalgamation

•Additional feature types e.g. lines

•Constraints e.g. feature alignment

•Higher/global level control e.g. staggered use of operators

•Alternative optimisation e.g. tabu

EXECUTION TIME IMPROVEMENT

Original Simulated Annealing Results

•Total number of configurations = 29^{321}

•Number of configurations evaluated = 342000

•Average Cost = 27 (best result = 22)

•Time taken = 40s (as reported in GeoInformatica 1998)

- too slow !

Improvement 1 - run on a faster machine

•Total number of configurations = 29^{321}

•Number of configurations evaluated = 341000

 $\bullet Cost = 26$

•Time taken = 13.5s

Improvement 2 - segment data

•Number of configurations evaluated dictated by annealing schedule and problem complexity

•Annealing schedule -

–Initial temperature T -Number of evaluations at each temperature -Temperature reduction factor

•Difficult problem will require many configurations

i.e. annealing schedule - high initial T

- many evaluations at each temperature
- small reductions in T

•Simple problem will require few configurations

i.e. annealing schedule - low initial T

- few evaluations at each temperature
- large reductions in T

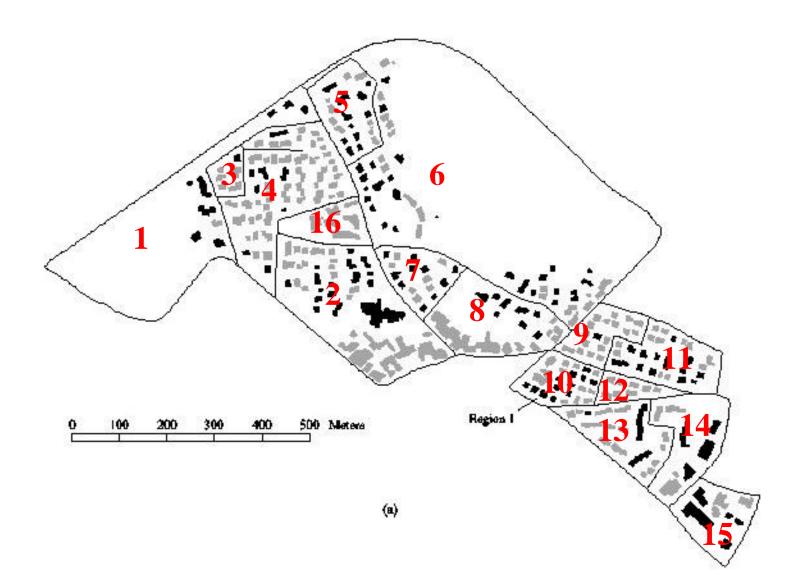
•If data is processed as a whole, annealing schedule must be set so at to be able to deal with most difficult part of data - leading to processing redundancy in parts where problem is simple

•Segment data - a separate, appropriate, annealing schedule for of each data subset

•Data segmented into autonomous regions i.e. an object in a particular region can never come into conflict with object belonging to any other region

Data segmented into 16 autonomous regions

•



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Segmentation Results

•Total number of configurations = 29^{321}

•Number of configurations evaluated = 79000

 $\bullet Cost = 27$

•Time taken = 3.2s

-75% saving

Problem

•Each of 16 annealing schedules arrived at via experimentation

•Need some method for automating the setting of annealing parameters (lots of work on this in general SA literature, such as automated setting of initial temperature T)

Improvement 3 - two stage annealing

•Simulated annealing

- high temp gets you to a low cost area is solution space

- low temp gets you to the local minimum

•Many authors suggest low temperature start annealing

-Need some method to stop solution from immediately getting caught in a local minimum

•Two stage annealing - replace annealing actions taking place at higher temperatures with a faster heuristic algorithm

> -fast heuristic algorithm - locates low cost area in solution space -simulated annealing (low initial T) - locates local minimum

TSSA algorithm

Stage 1 simulated annealing - high initial temperature - rapid cooling

Stage 2

simulated annealing/sintering

- low initial temperature
- gradual cooling

TSSA Results

•Total number of configurations = 29^{321}

•Number of configurations evaluated = 74000

 \bullet Cost = 26

•Time taken = 3.1s

-75% saving

Improvement 4 - combine segmentation & TSSA (i.e. apply TSSA to each of the 16 regions in turn)

•Total number of configurations = 29^{321}

•Number of configurations evaluated = 37000

•Cost = 26

•Time taken = 1.6s

- 88% saving