

Segmentation for 3D building generalisation

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Content

Algorithm for Segmentation

Analysis and Generalisation

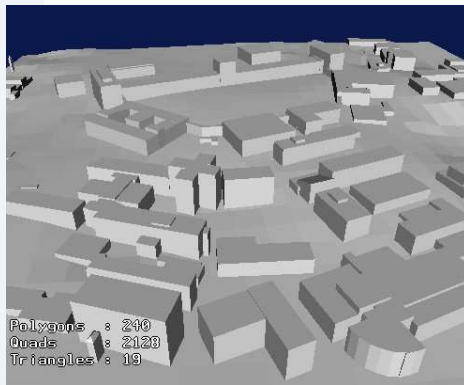
Geometric classification of features

Additional common sense knowledge

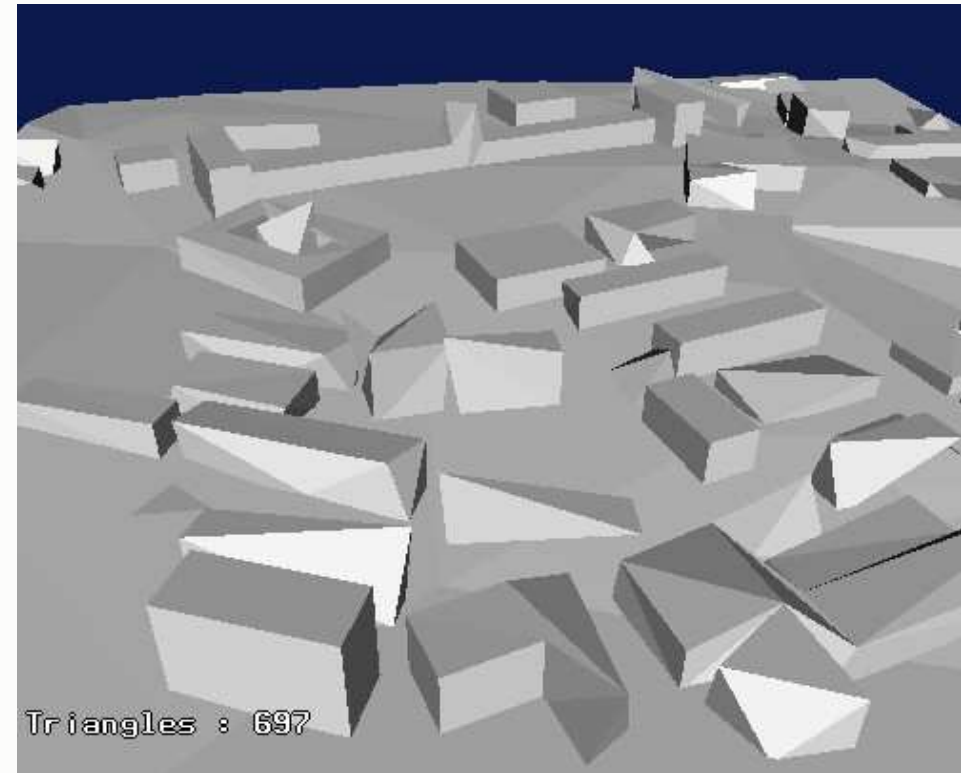
Conclusions

Introduction

- ▶ elimination of single vertices is not suited for 3D building generalisation



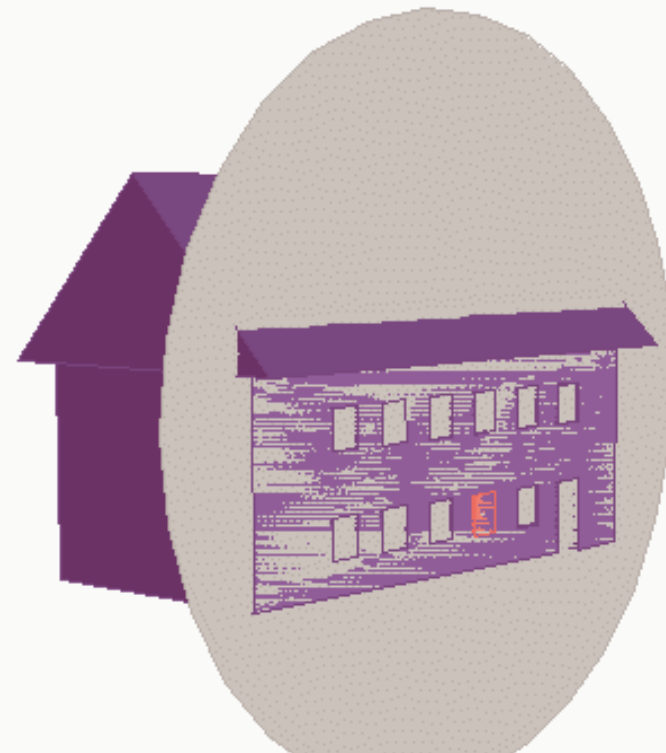
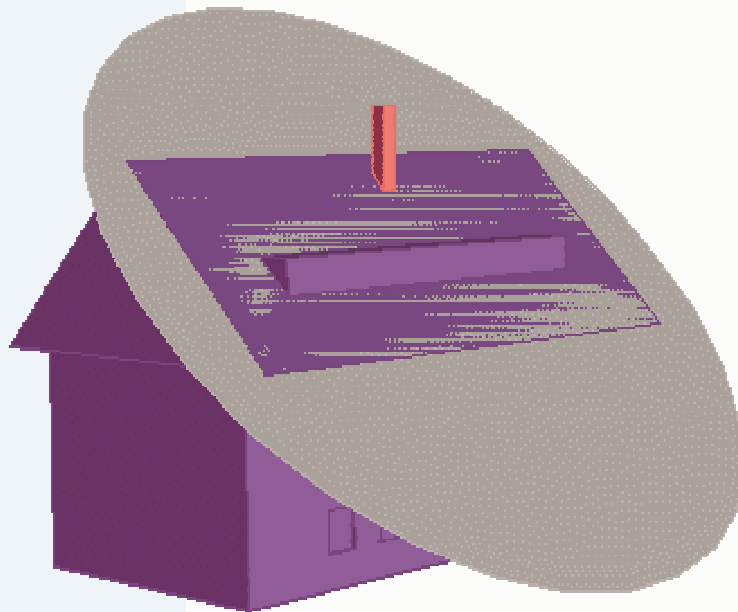
- ▶ examine parts
 - size
 - semantic / significance



→ Decompose the complex object in smaller “meaningful” parts to get small objects which can be separately handled.

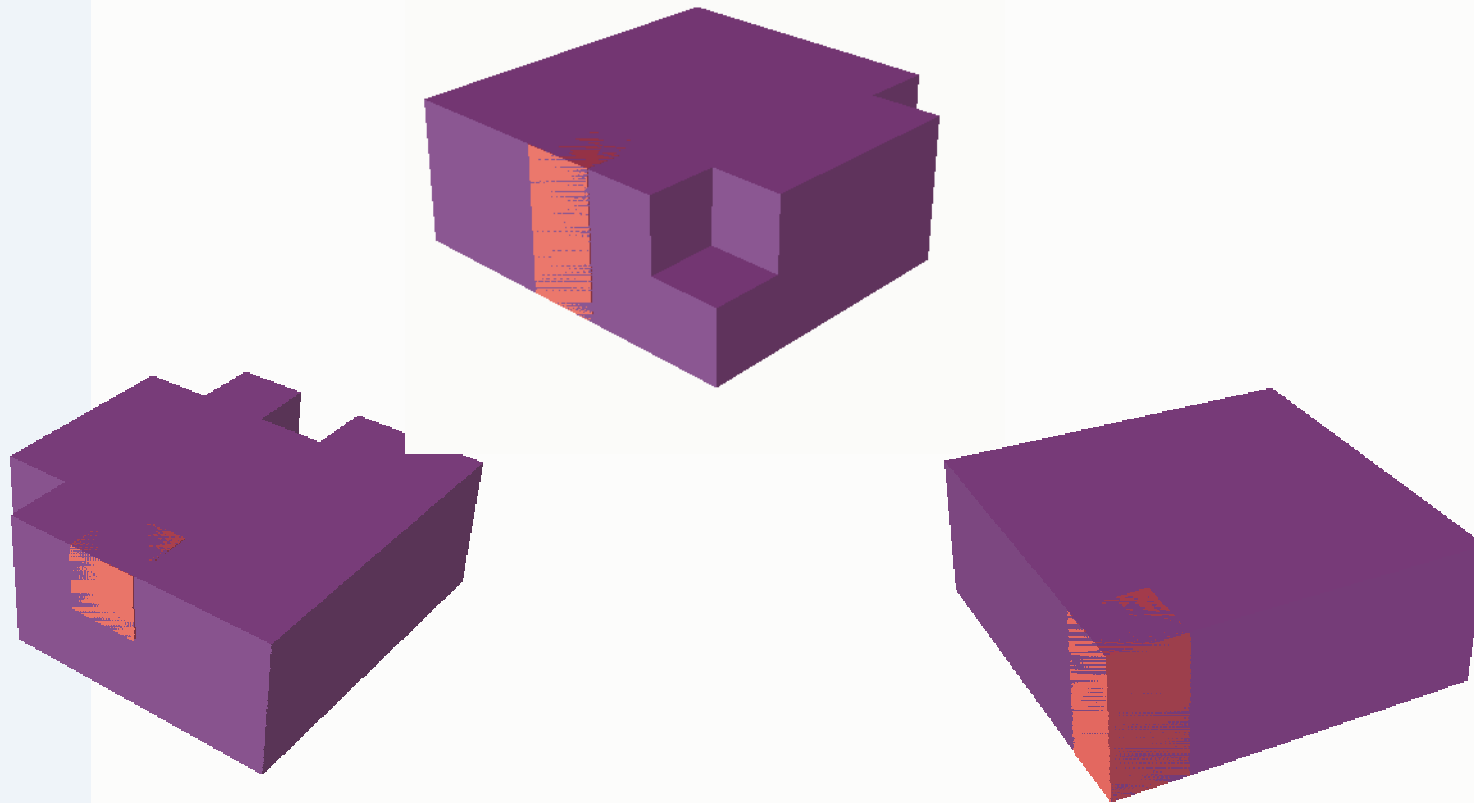
Segmentation

- ▶ using the algorithm of Ribelles, Heckbert ... to decompose a polyhedron in meaningful parts (so called features)
- ▶ intersect the polyhedron with one or more plans of its boundary to cut protrusions or fill holes.

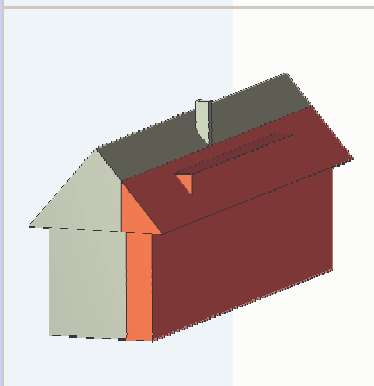
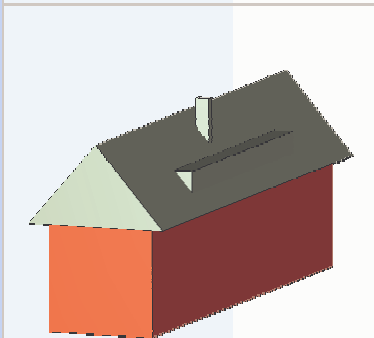
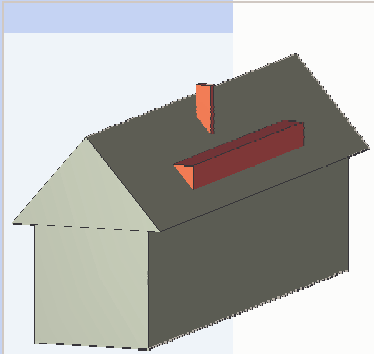


Complex Holes

- ▶ to fill complex holes more than one split-plane is needed



Quality of a split



- ▶ quality after Ribelles et. al

$$q = \frac{\text{area of the new inserted face}}{\text{area of the origin coplanar with the split plane}}$$

(q lower -> better)

- ▶ more than one feature → evaluate them separately

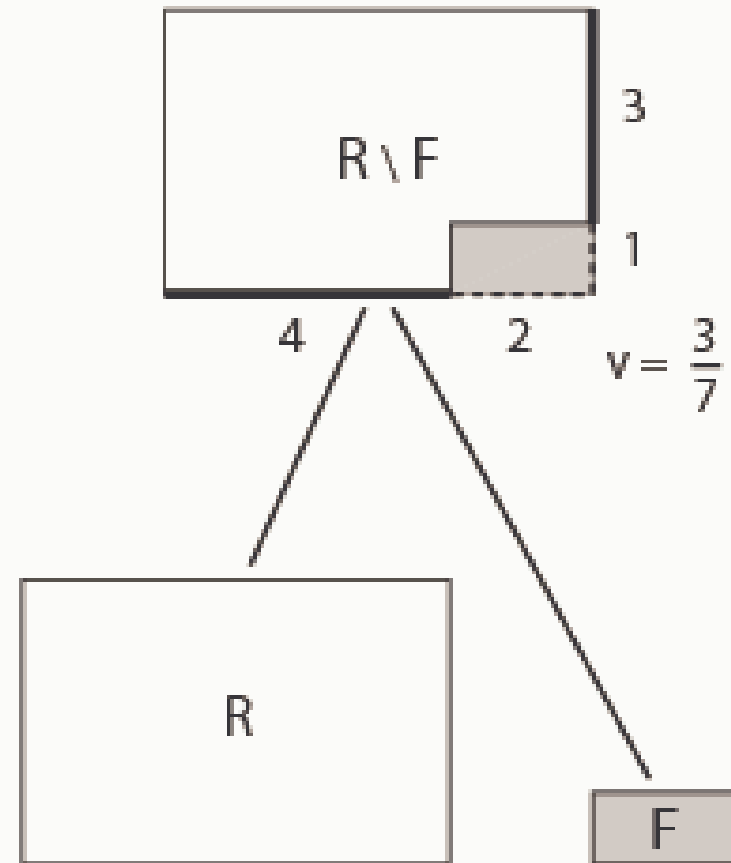
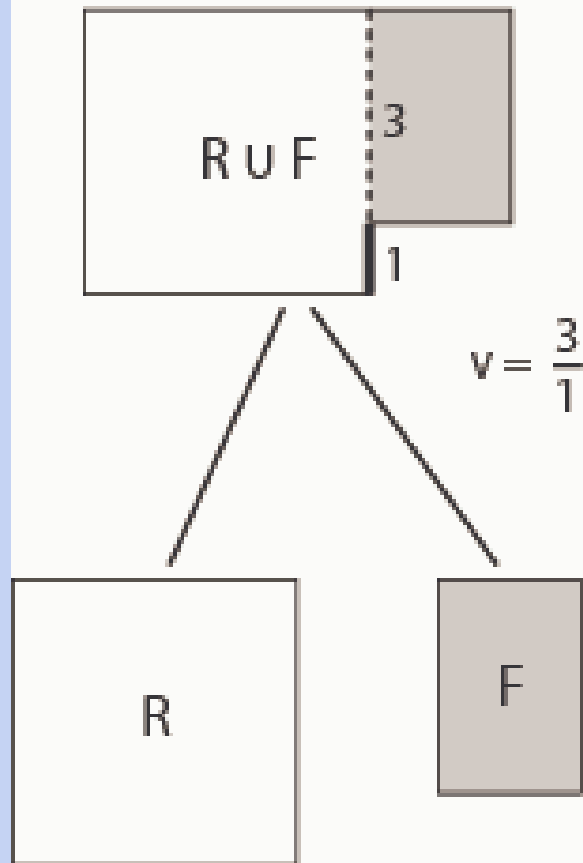
- ▶ validation of the split

$q < 1$ → new area smaller than existing area

- ▶ using only the best split

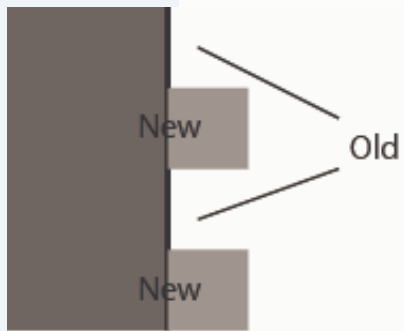
- ▶ split the two parts recursively

Quality value

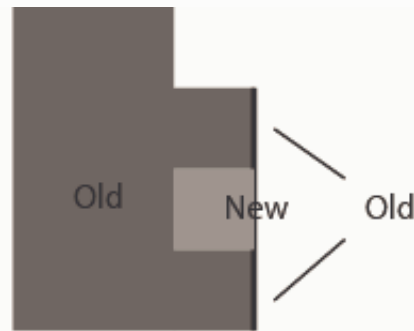


..... new faces inserted
— faces in the splitting plane

Quality Value



Old =2, 2x New =1

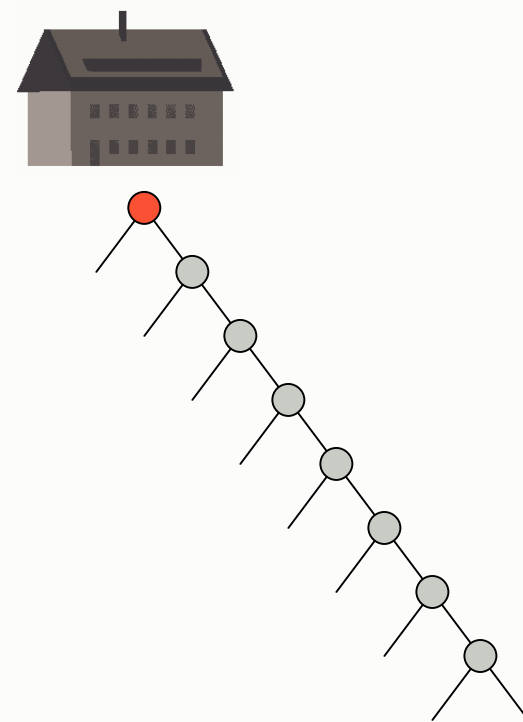
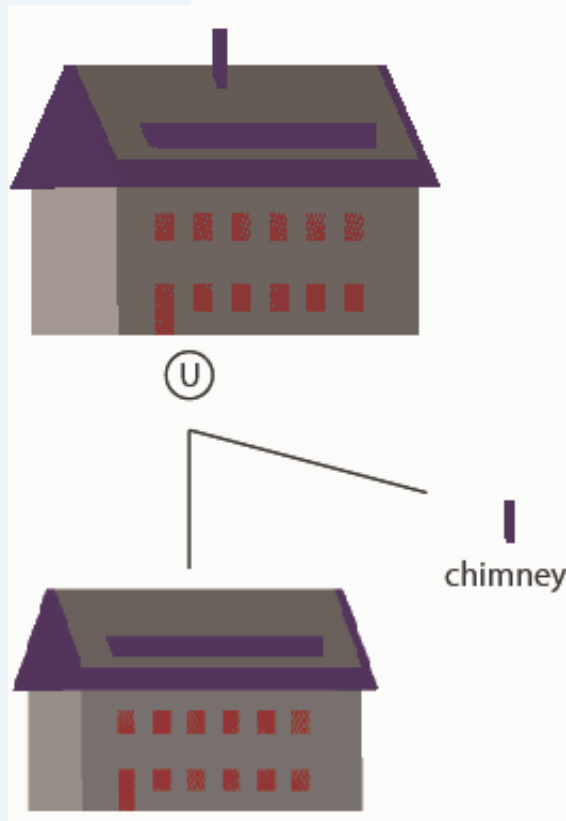


Old =2, New =1

Old = area of all facets laying in the split plane

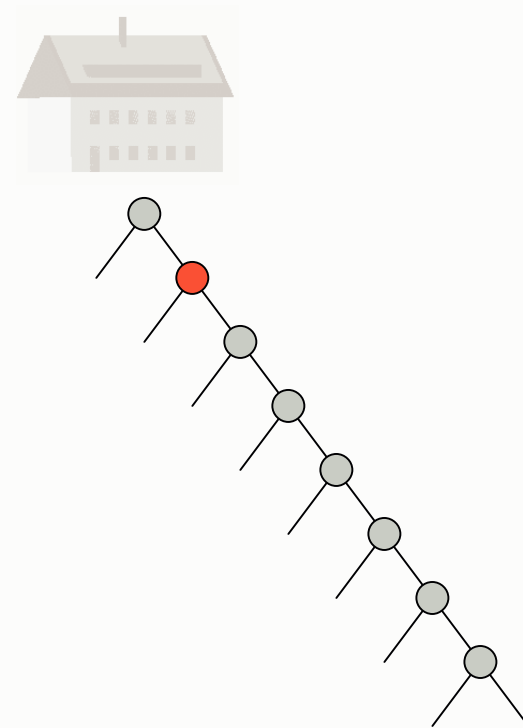
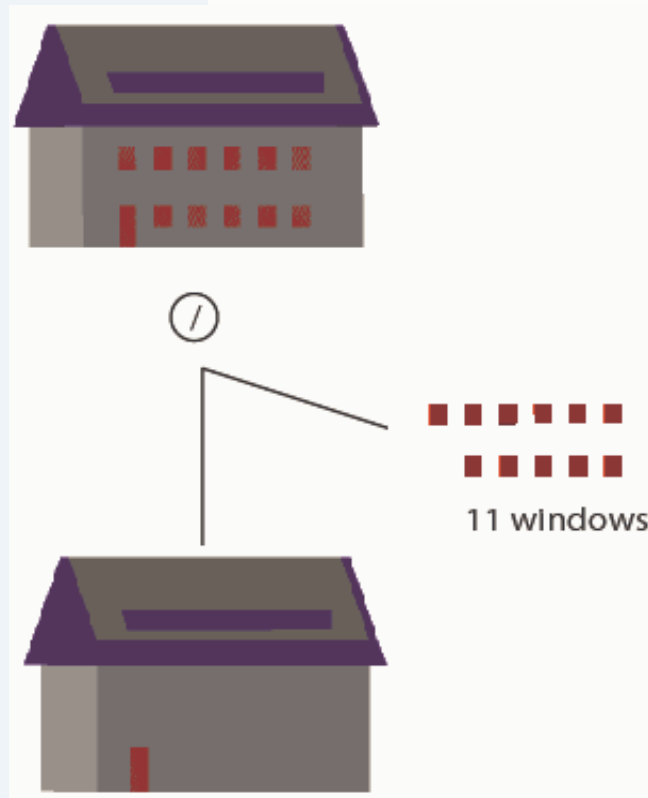
New = area of the faces inserted to separate the parts

Sample building - Step 1



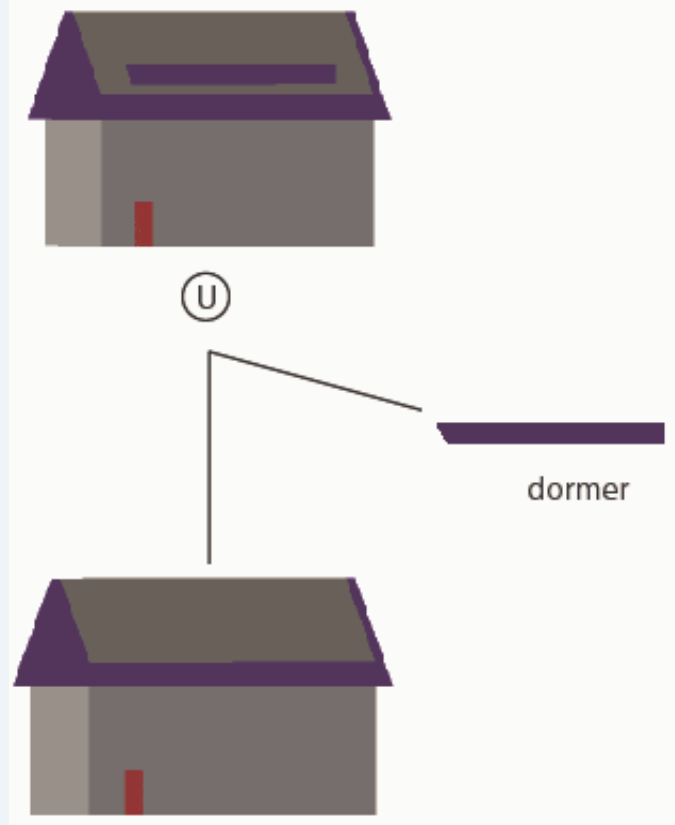
$q = 0.003$

Sample building - Step 2

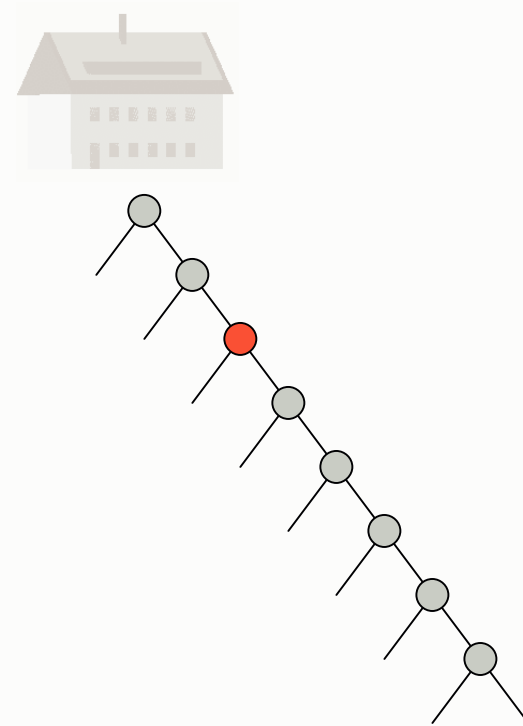


$q = 0.014$

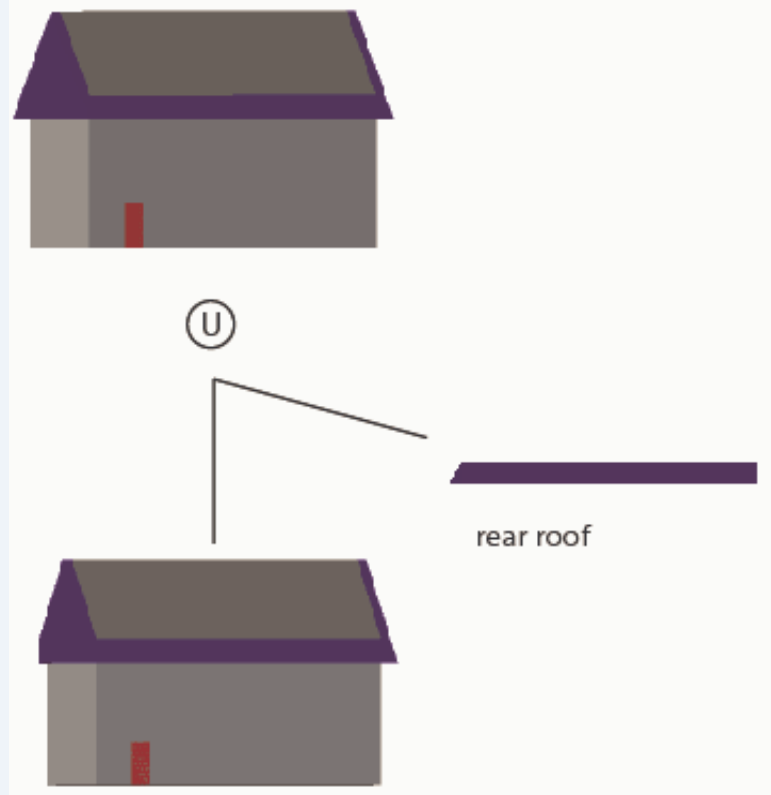
Sample building - Step 3



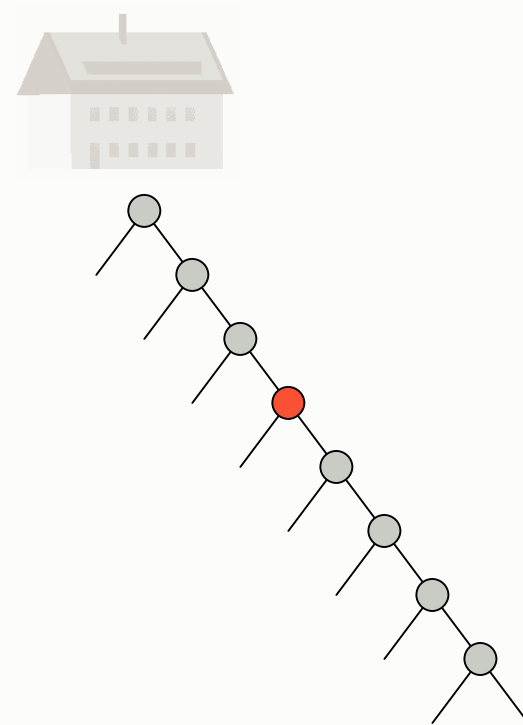
$q = 0.162$



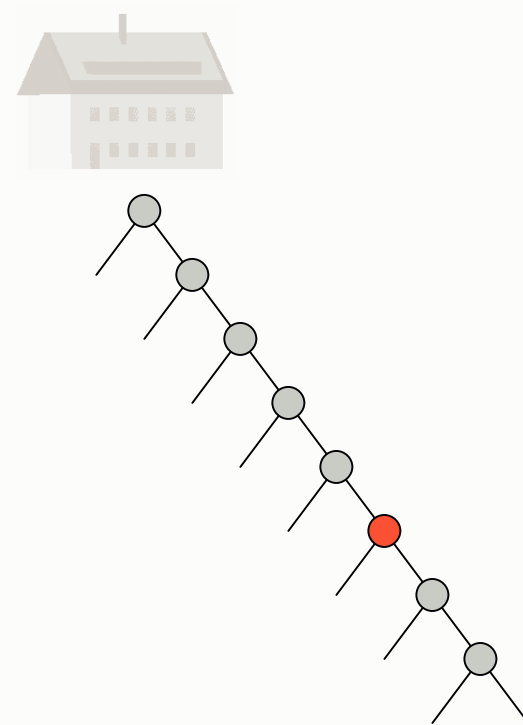
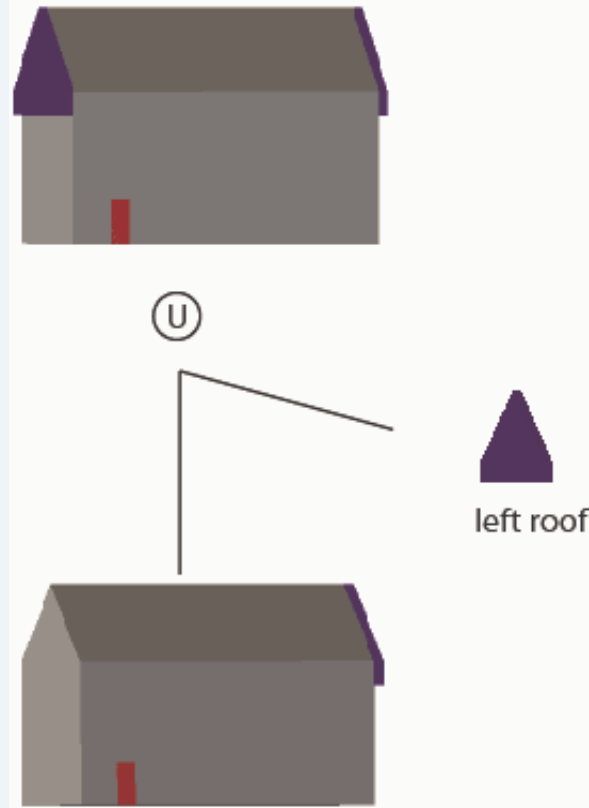
Sample building - Step 4



$q = 0.205$

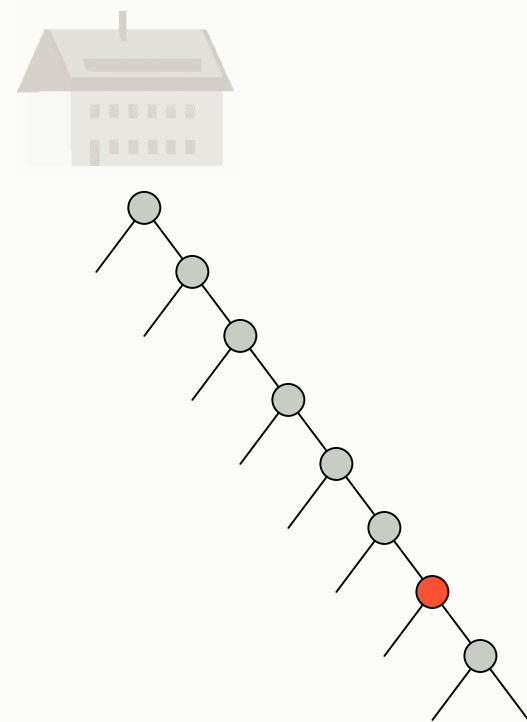
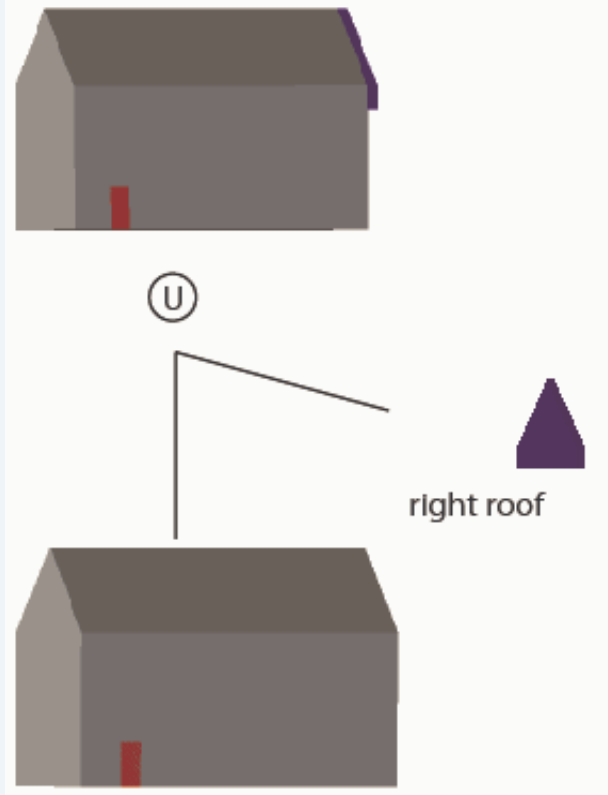


Sample building - Step 6



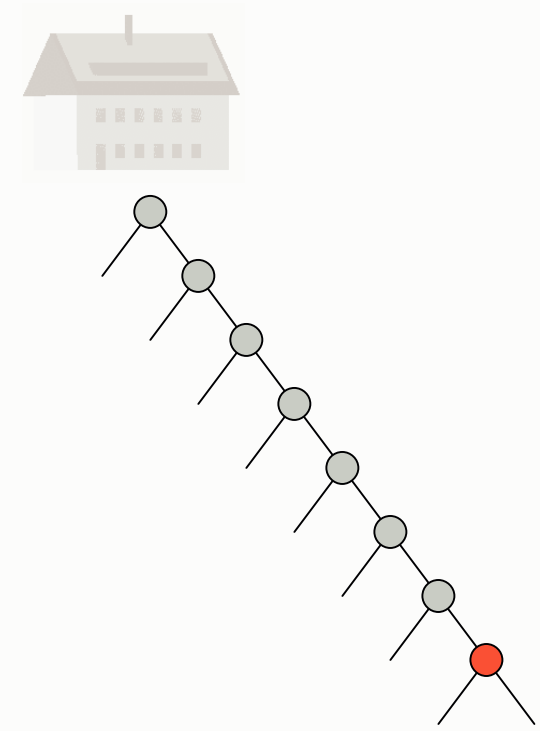
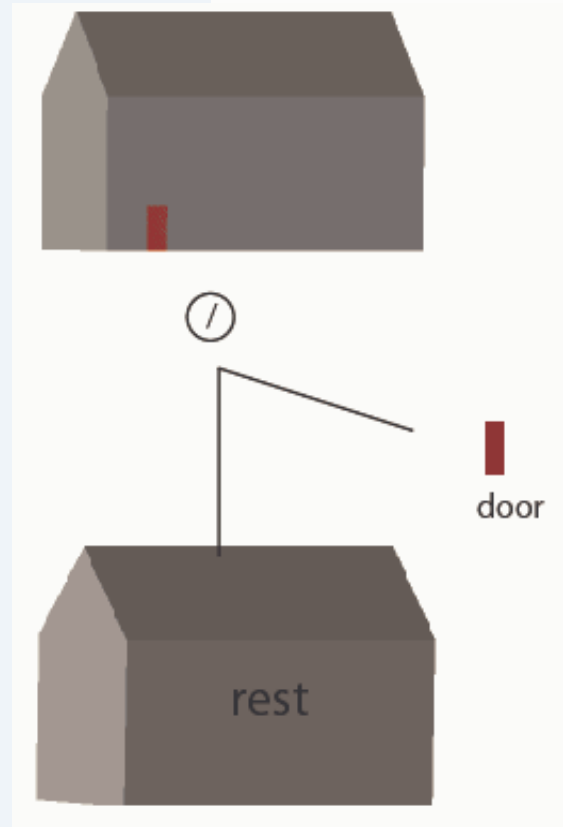
$q = 0.517$

Sample building - Step 7



$q = 0.517$

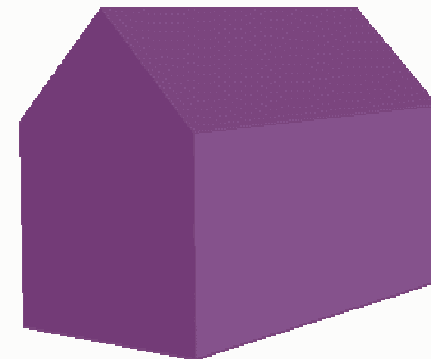
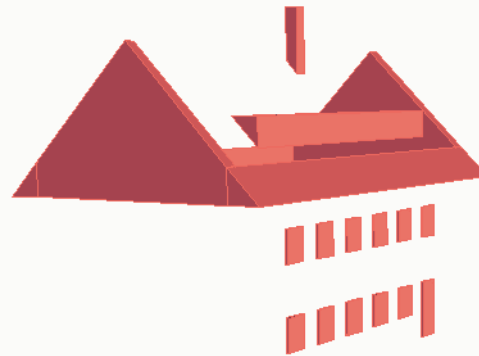
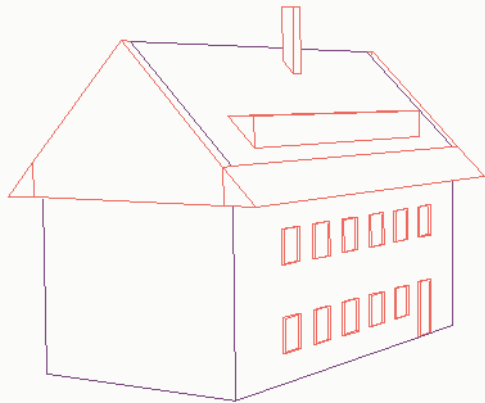
Sample building - Step 8



$q = 0.009$

Result of segmentation

- ▶ convex parts (protrusions and holes)
- ▶ CSG-tree (hierarchy of splits)
- ▶ not a generalisation!



Complexity of segmentation

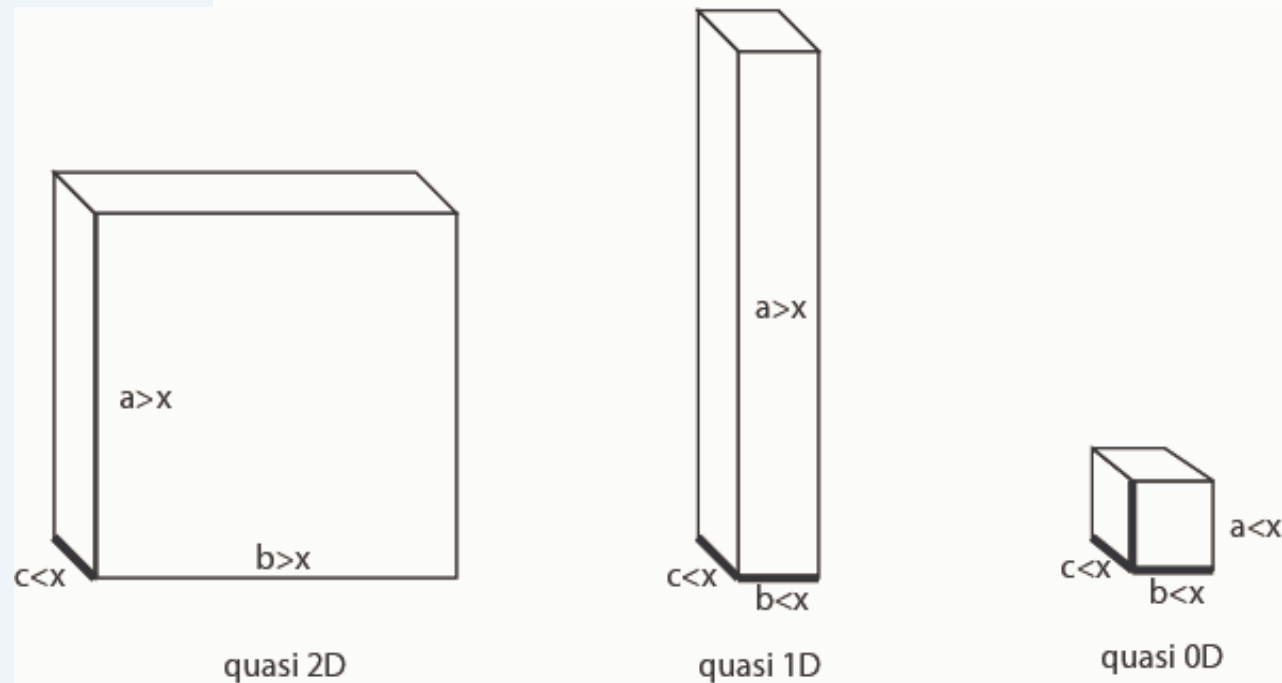
- ▶ brute force: “try all combinations of planes for all parts”
 - $O(m \cdot n^{2k})$
 - n ... count of planes
 - m ... count of parts
 - k ... count of planes used at the same time

- ▶ optimization:
 - only planes with different normals at once
 - only anti parallel planes with positive distance
 1. cut and fill with one plane at once (→ only simple holes)
 2. fill complex holes with 2, 3 and 4 planes

Generalisation (generic determination)

- ▶ decide only on geometric parameters
 - size – but which?
 - extents
 - area
 - volume
 - is it observable?
 - visible area

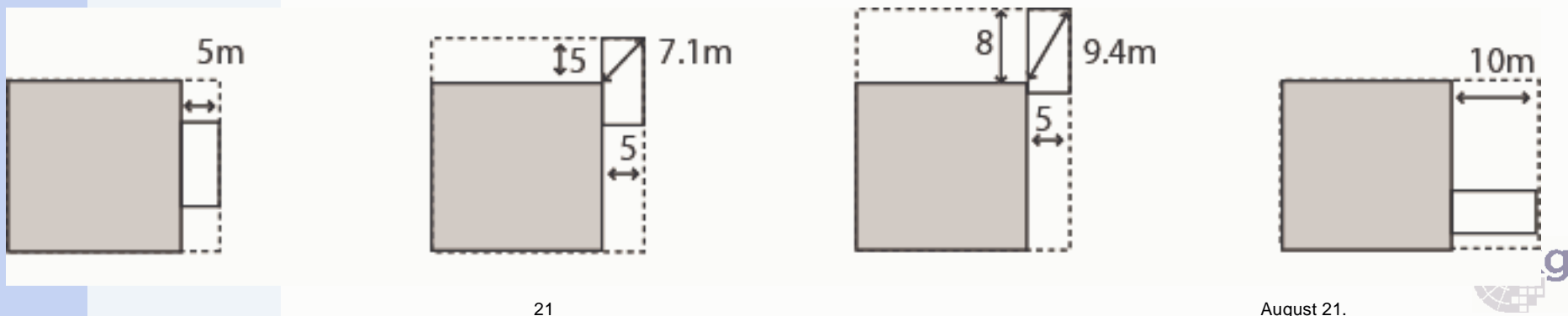
Quasi k-D



- ▶ quasi 2D – laminar - small in 1 dimension – a large area
- ▶ quasi 1D – linear – small in 2 dimensions – a large length
- ▶ quasi 0D – punctiform – small in all 3 dimensions

Quick-test for visibility using a bounding box

- ▶ sorting sides in descending order ($a \geq b \geq c$)
 - if $c > x_c \rightarrow$ no generalisation necessary
 - $a < x_a \rightarrow$ quasi 0D \rightarrow omit, enlarge, ...
 - $b < x_b \rightarrow$ quasi 1D \rightarrow omit, enlarge, ...
 - $A = a b < x_A \rightarrow$ omit, enlarge, ...
 - only quasi 2Ds are left
- ▶ Depending on the position of quasi-2Ds there is a smaller or a bigger difference in visibility.



Object depending Generalisation

- ▶ recognition of the “function” (window, door, roof, balcony, ...)
- ▶ attributes;
 - orientation
 - height
 - context
 - similarity (size) in given neighbourhood (distance)
- ▶ knowledge
 - typical size / orientation / positions
 - typical height of stories

Conclusions

- ▶ algorithm of Ribelles et al.
 - is suited to separate buildings in meaningful parts
 - needs optimization to reduce runtime
- ▶ based on the derived features
 - generalisation with generic determination gets possible
 - some optimizations of the CSG tree could become necessary
- ▶ object depending generalisation
 - symbolisation, aggregation, typification need semantic information
 - recognition of the semantic type (roof, window ...)

End

- ▶ Thank you for listening.