



Radius Clarity Automated Generalisation

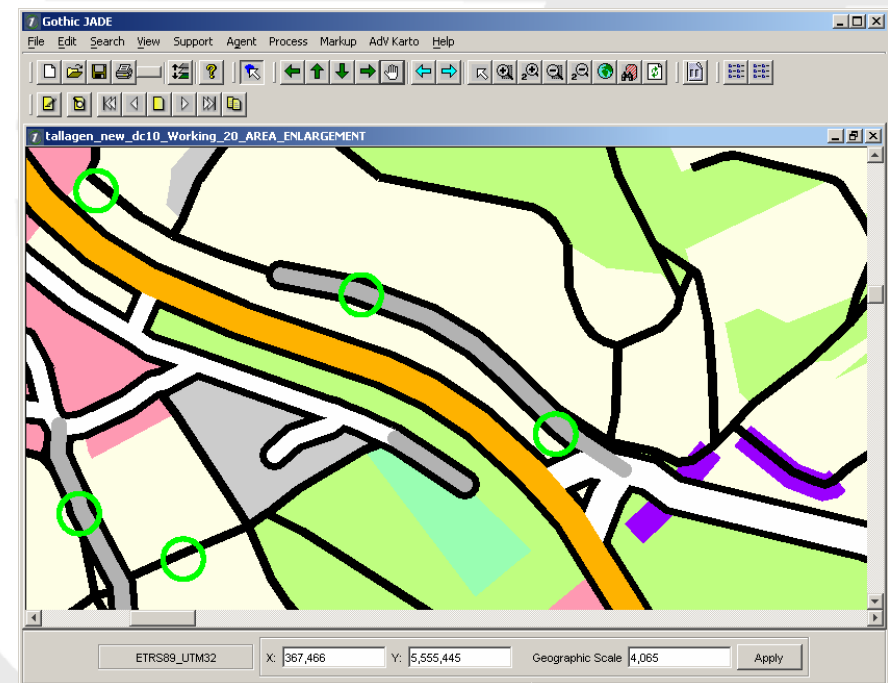
Graham Stickler
21st June 2008

Content

- Brief overview of Radius Clarity
- Automated Generalisation workflow
- Model Generalisation results
- Cartographic Generalisation results
- Explain Agent Technology
- Planned Future Developments

Radius Clarity is 1Spatial's platform for automated generalisation.

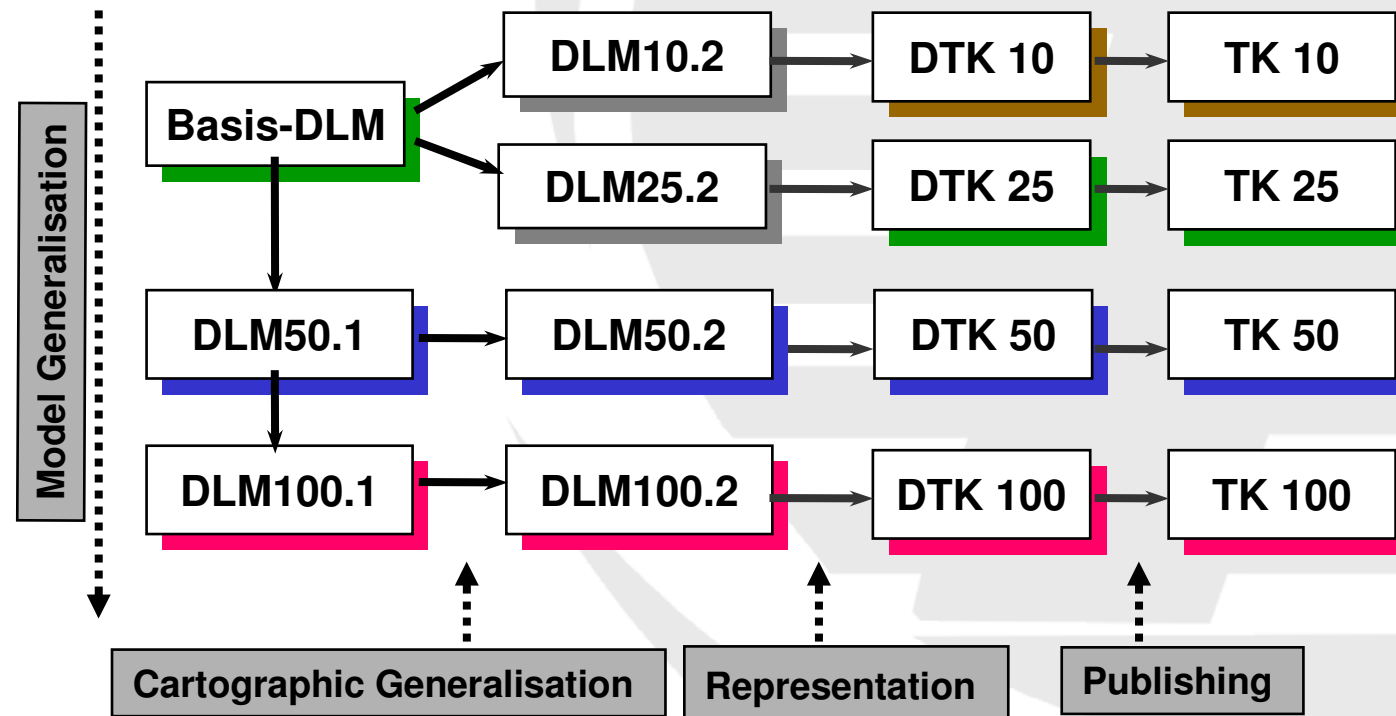
- Toolkit for building automated generalisation workflows
- Derives new mapping products automatically from existing data.
- Provides an environment to develop and research new generalisation algorithms.



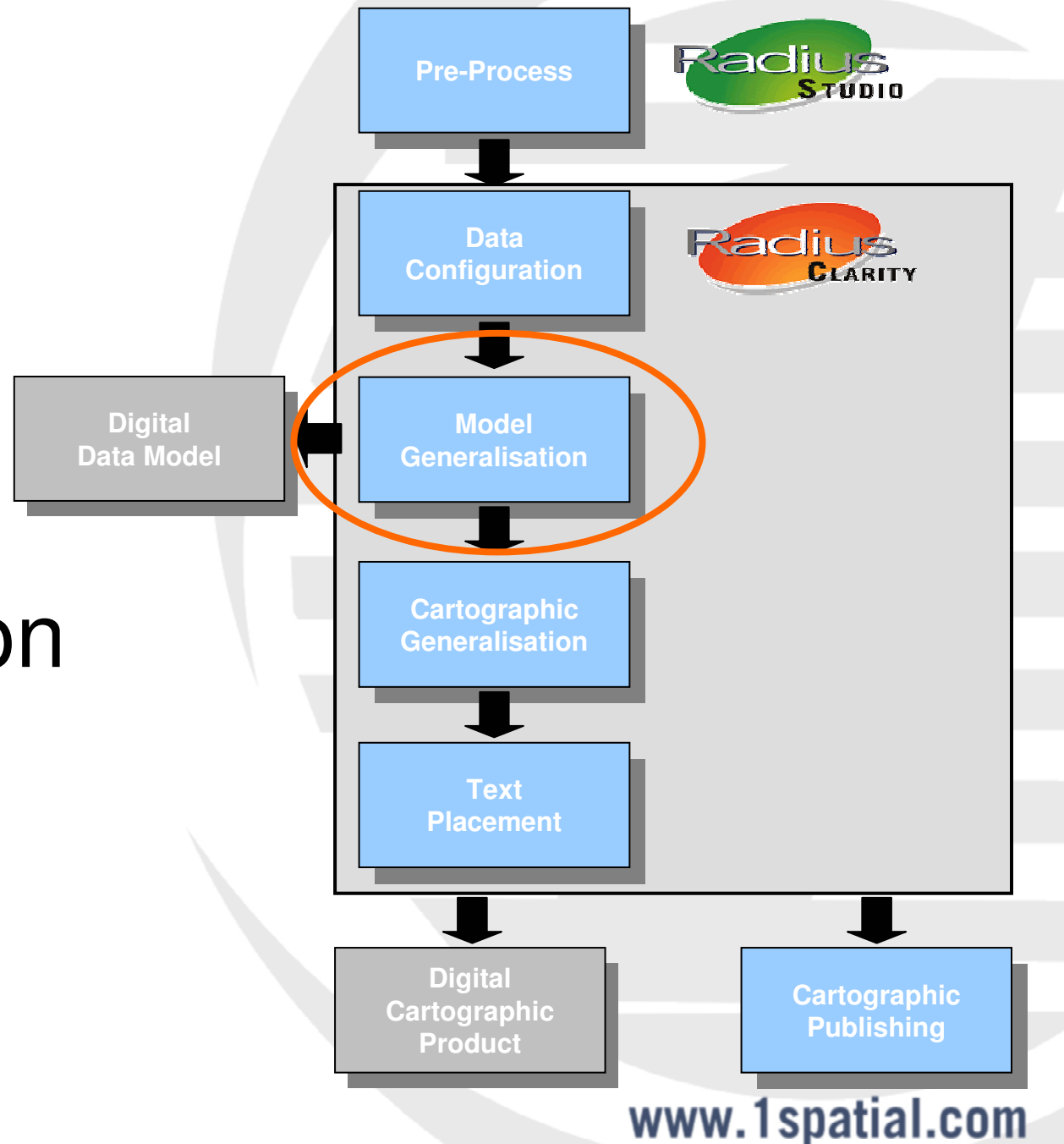
AdV Project

Advantages of the Agent-Technology

- Scale independence



Automatic Generalisation Workflow



Model Generalisation

Model Generalisation is the reduction of the amount of source data to a level suitable for the target scale. This is achieved by;

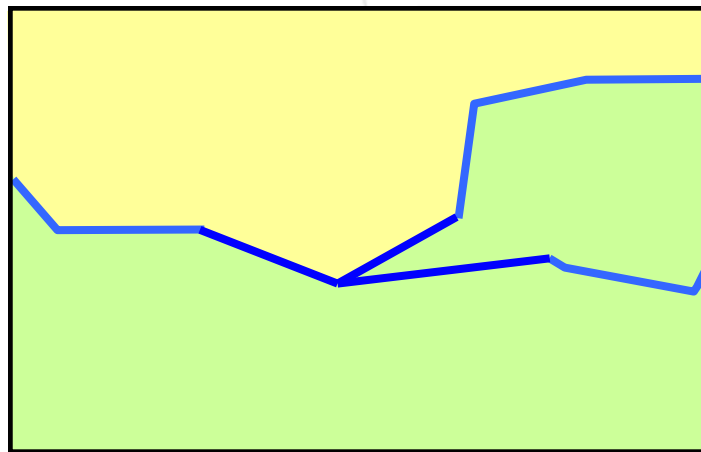
- Removing feature classes that are not visualised at the target scale
- Amalgamating or removing small features while retaining topological connectivity
- Filtering unwanted detail from features

Features retain their real world coordinates (not displaced or exaggerated etc).

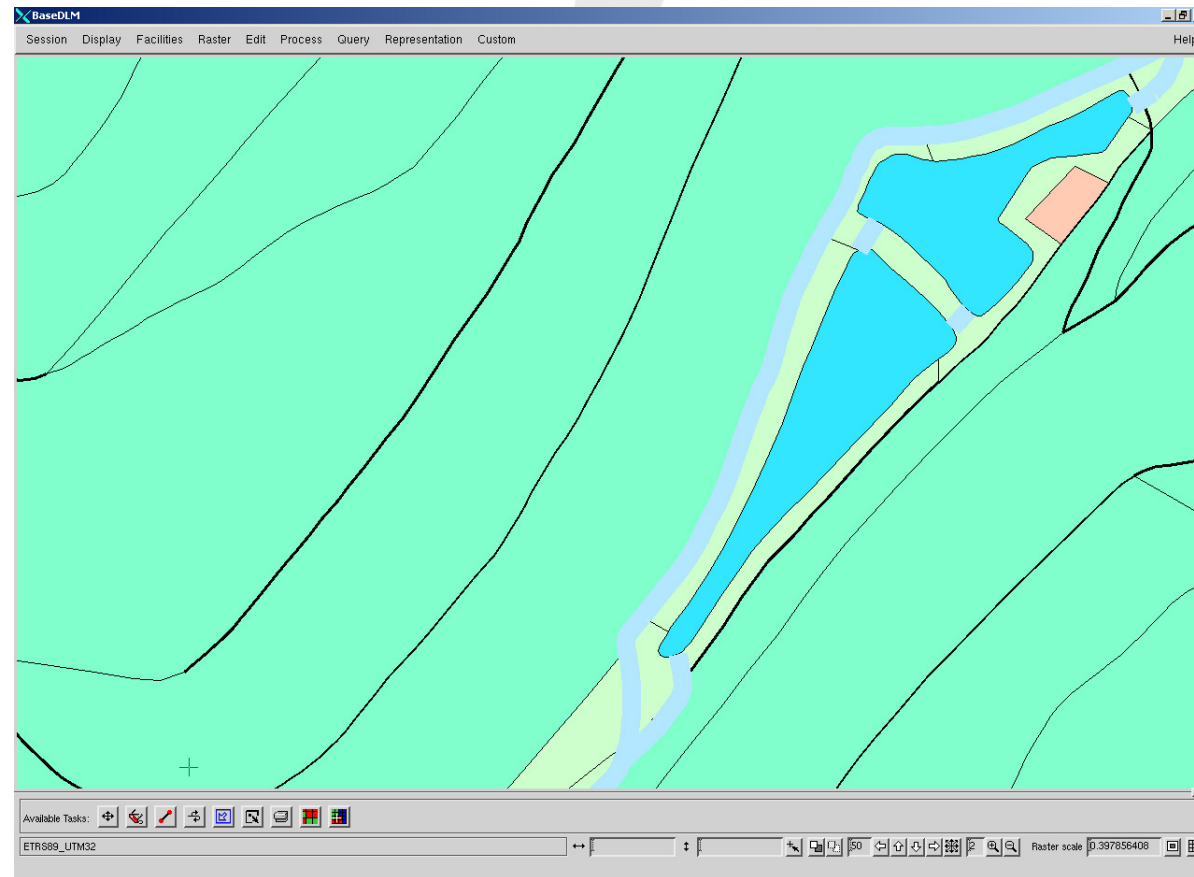
Area Merging (merging base areas)

Requirement

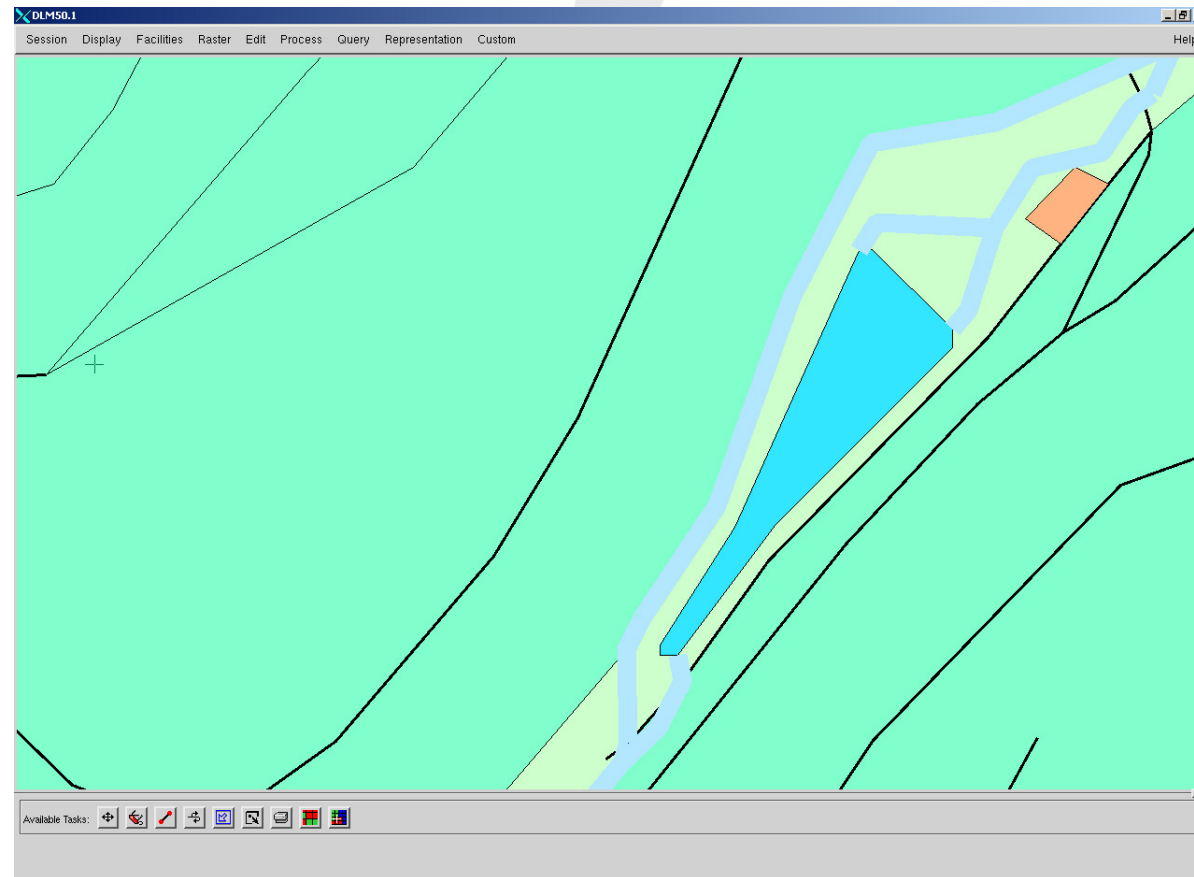
- Delete lake objects that are too small for representing at 1:50,000
- If the lake has a connection with two or more rivers then connectivity must be maintained
- Merge all the parts of the deleted lake into the surrounding areas



Area Merging (merging base areas)



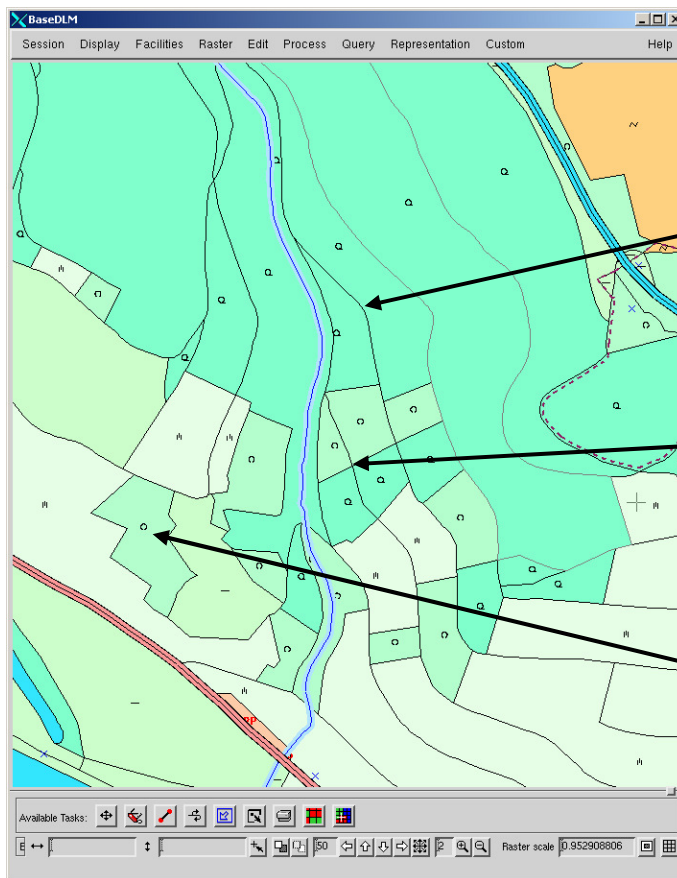
Area Merging (merging base areas)



Model Generalisation Results

BaseDLM

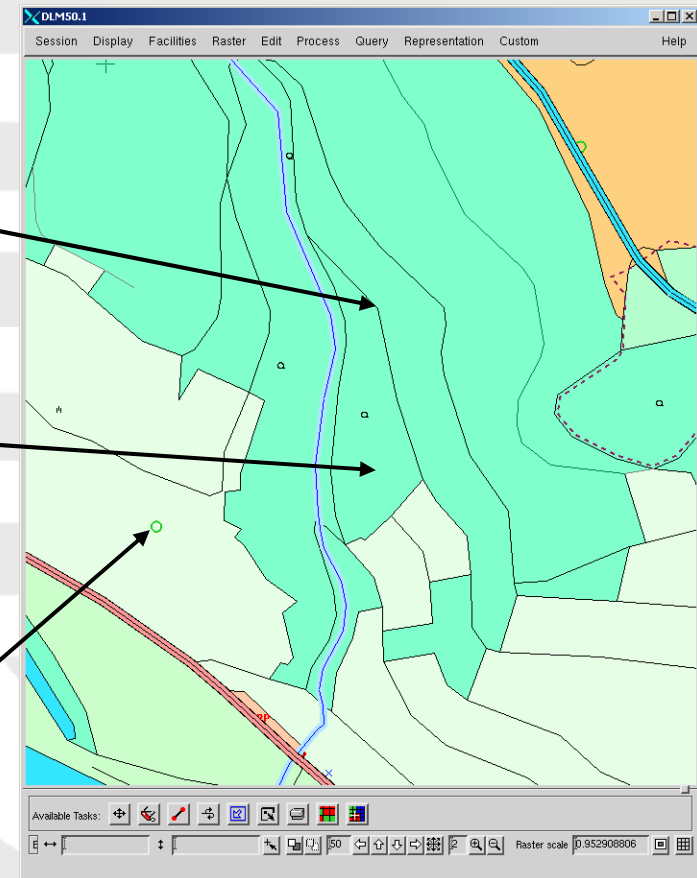
DLM50.1



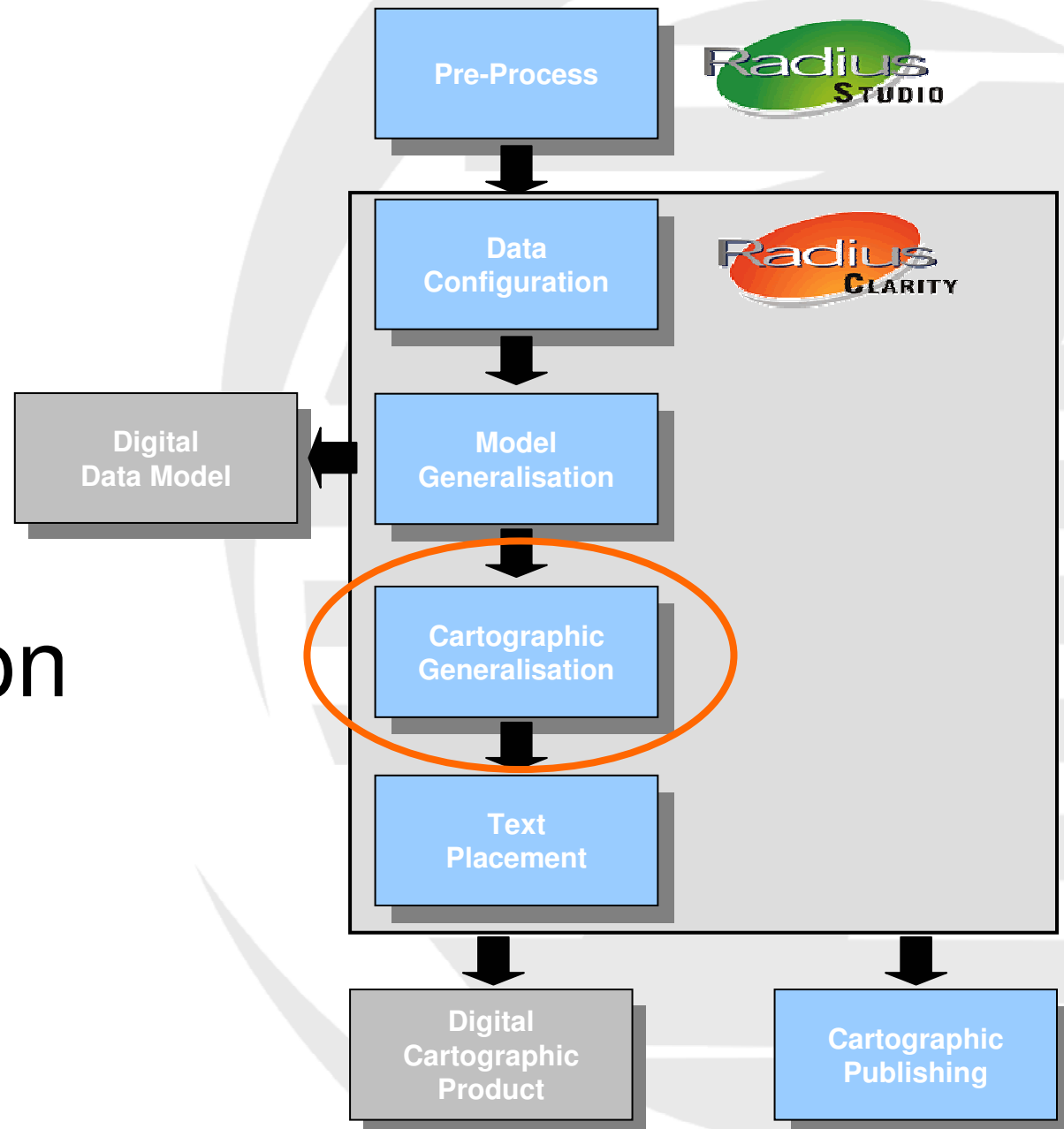
Line Filtering
(Point Reduction)

Area Merging

Geometry Change
(Area to Point)



Automatic Generalisation Workflow



Cartographic Generalisation

Cartographic Generalisation is concerned with the detection and resolution of conflicts between map objects for representation at the target scale. This is achieved by;

- Simplification
- Typification
- Displacement
- Enlargement
- Diffusion
- Exaggeration

Agent Approach

- Map objects (e.g Roads, Buildings) are made Agents, making them self aware

Measures: Indicating the state and surroundings of the object

“How big am I?”

“How close am I to my nearest neighbour?”

Constraints: Asserting the target values

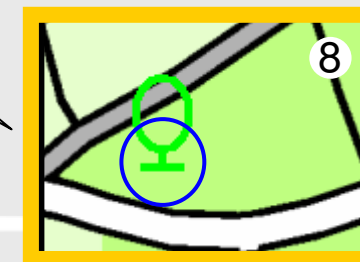
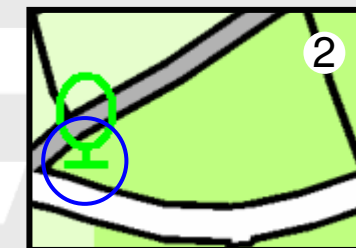
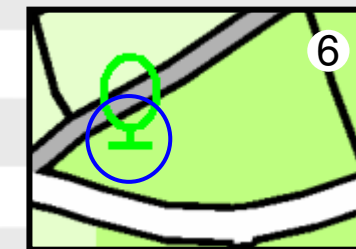
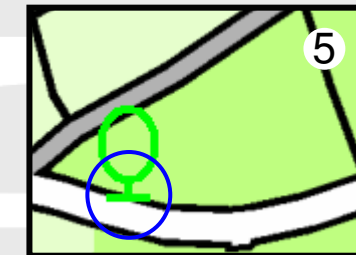
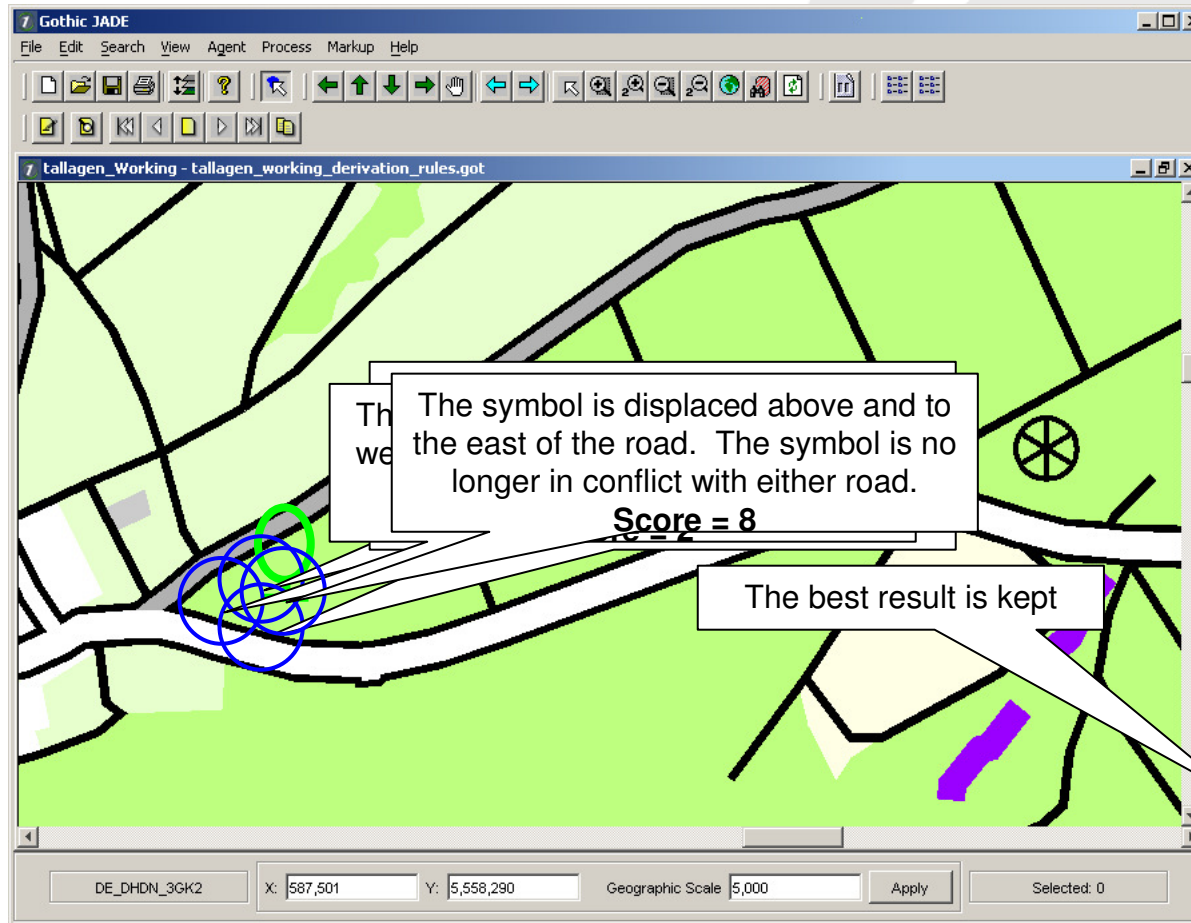
“I am too small for the target scale”

“I am too near the next building”

Algorithms: Change the state in order improve the situation

- Agents enact different generalisation algorithms, to find and keep the best result

Agent Lifecycle



Data Cases

KARTO Project – Automatic Cartographic Generalisation – Data Cases

3

DC1: Typification¹ of Identical Point Symbols

Ref: AKG 6.1.1 a)

Linked to clarification of Issues 005, 006, 010, 103, 216, 222, 229, 230, 302, 303.

1. *Brief description*

Detects and resolves overlapping symbols using typification to place a smaller number of symbols in positions representative of the original placement.

2. *Target object types*

See target object types table².

3. *Flow of processing*

3.1. *Basic flow*

- 1 Objects which have the same signature number and overlapping bounding geometries³ (box, circle, or buffer), but which are not separated by any line object are collated
- 2 Number of symbols to maintain is determined by Topfer's Radix Law⁴.
- 3 Remaining symbols are placed in positions representative⁵ of the original placement of symbols

3.2. *Alternative flows*

- 1 At 1: If the number of symbols is 2 and the overlap of the bounding geometries of the symbols does not exceed 80%⁶, the data case terminates
- 2 At 3: If the number of symbols to place is 1, it shall be placed at the centre of gravity⁷ for the group.
- 3 At 3: If one single symbol has a NAM, that symbol must be one of the remaining symbols, and should occupy the representative position closest to the original position of the symbol.
- 4 At 3: If two or more symbols have a NAM, the NAM must be removed from all positional objects.

4. *Pre-conditions*

The ~~can~~ overlap between the bounding geometries buffered by the applicable minimum ~~between~~ symbols with the same signature number



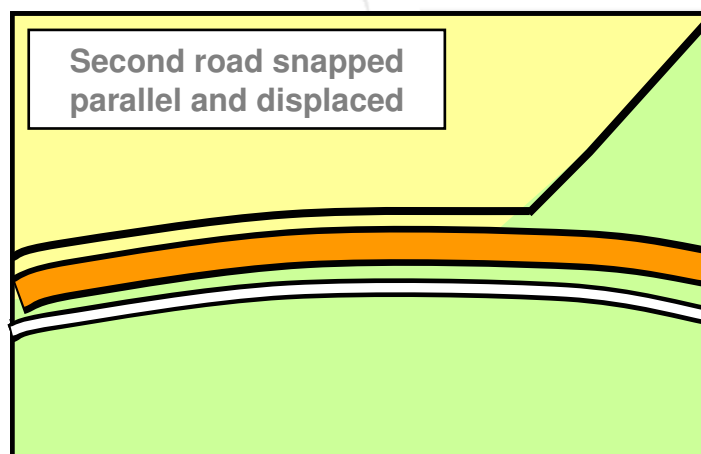
Spatial



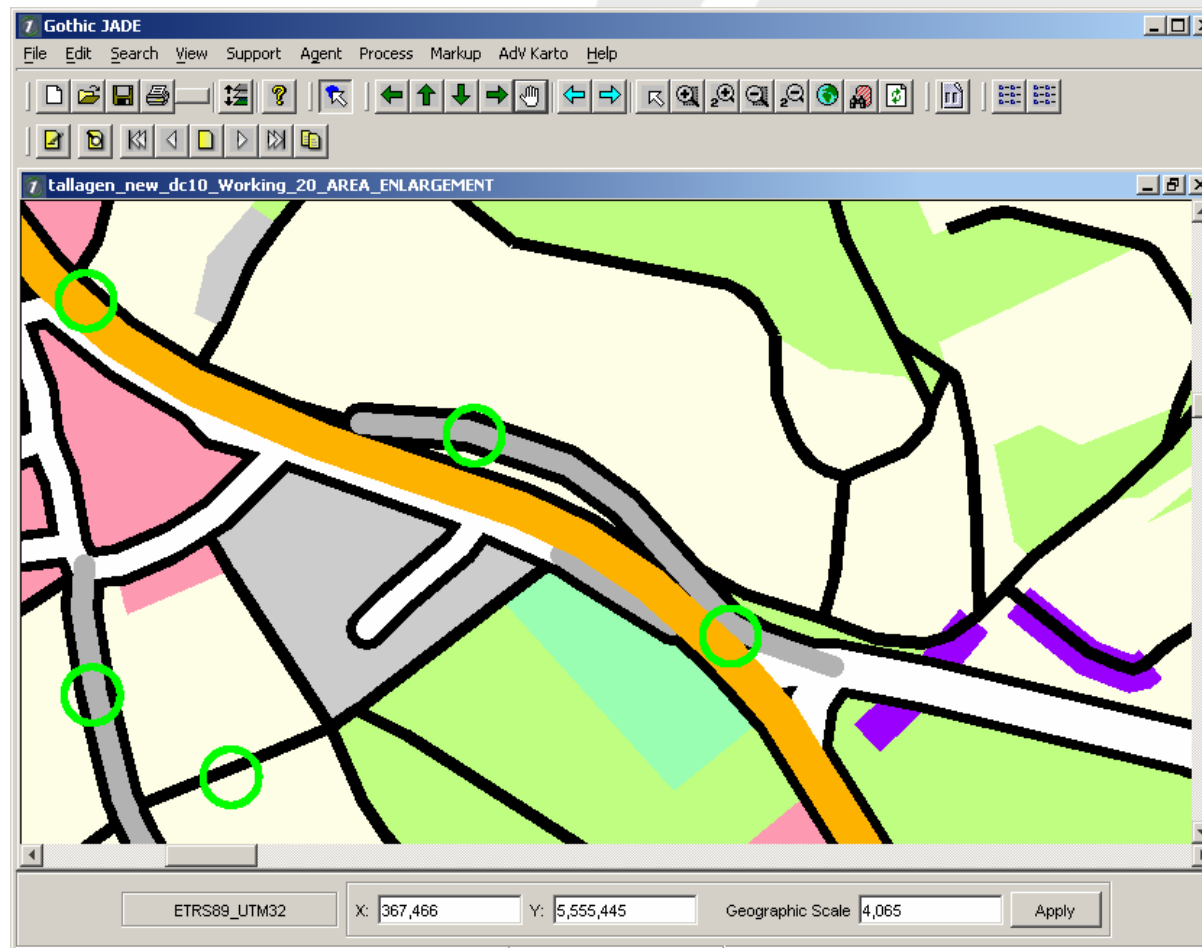
Snapping Lines (to be parallel)

Requirement

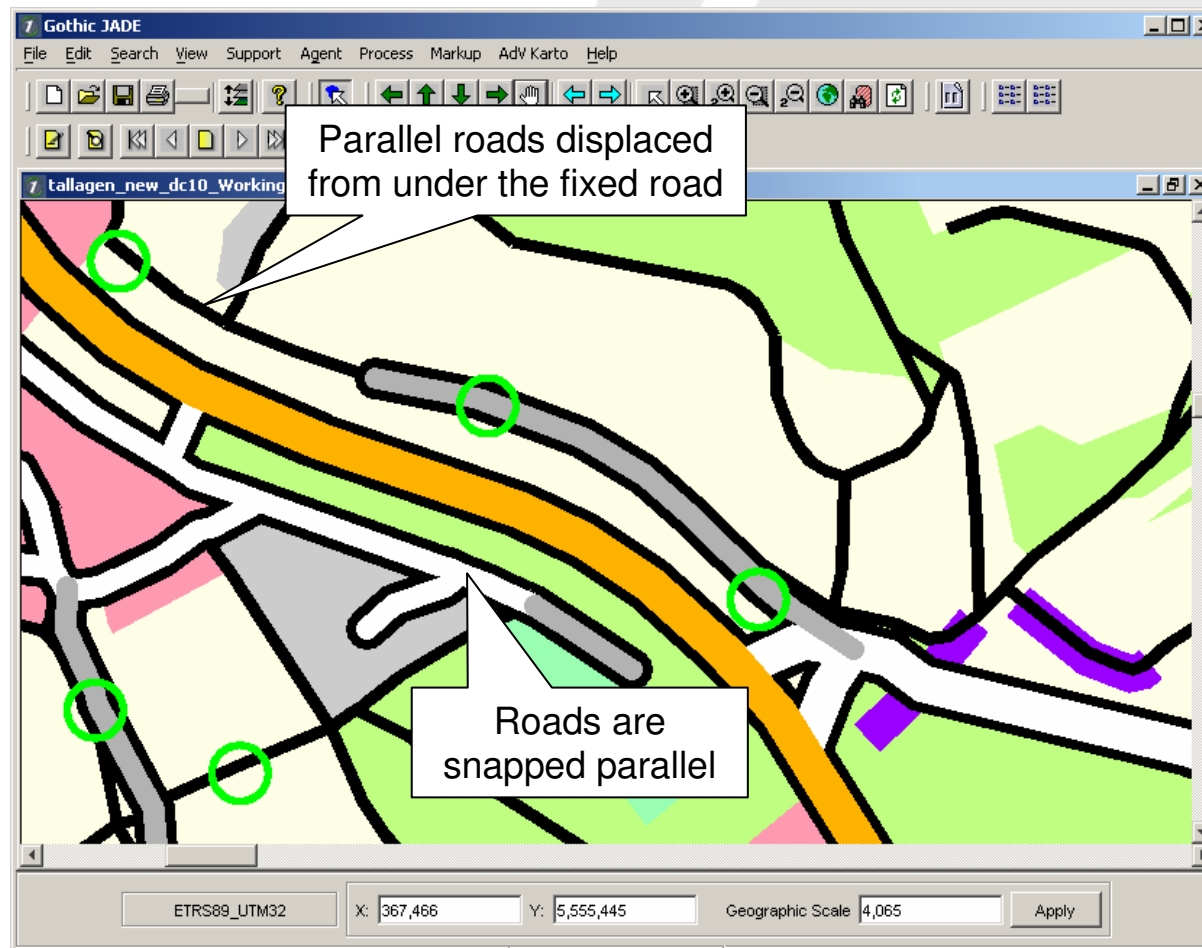
- Lines that run close together should be snapped parallel
- The line object with the highest priority should remain fixed
- The two objects are displaced to an appropriate distance for representing at 1:50,000
- Adjacent objects are diffused to preserve topological relationships



Snapping Lines (to be parallel)



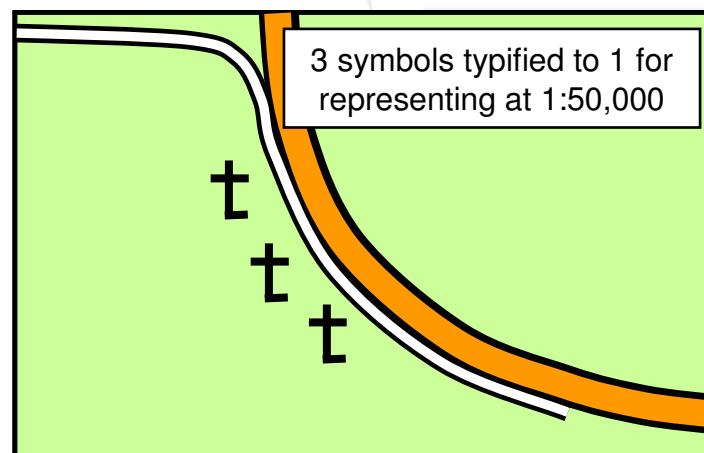
Snapping Lines (to be parallel)



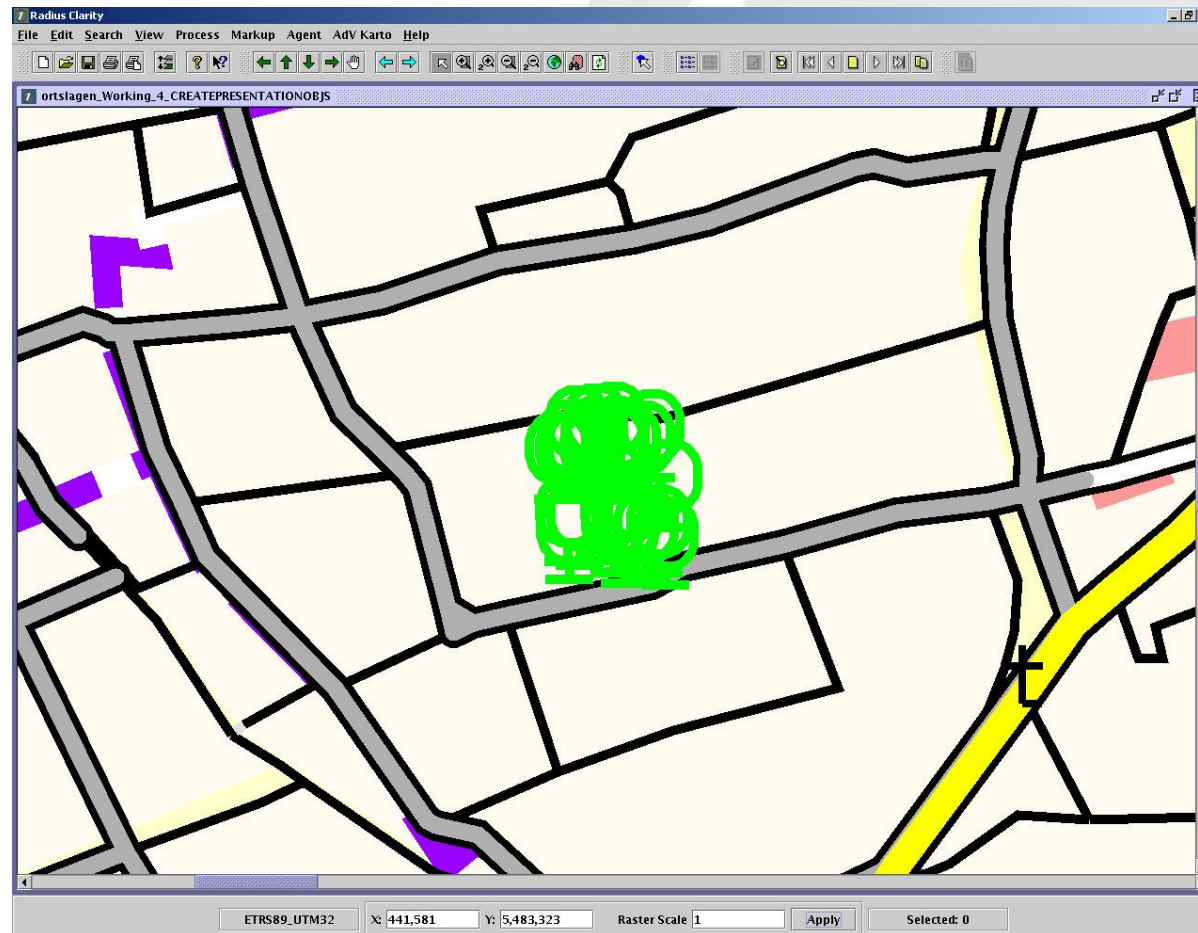
Typification (of identical point symbols)

Requirement

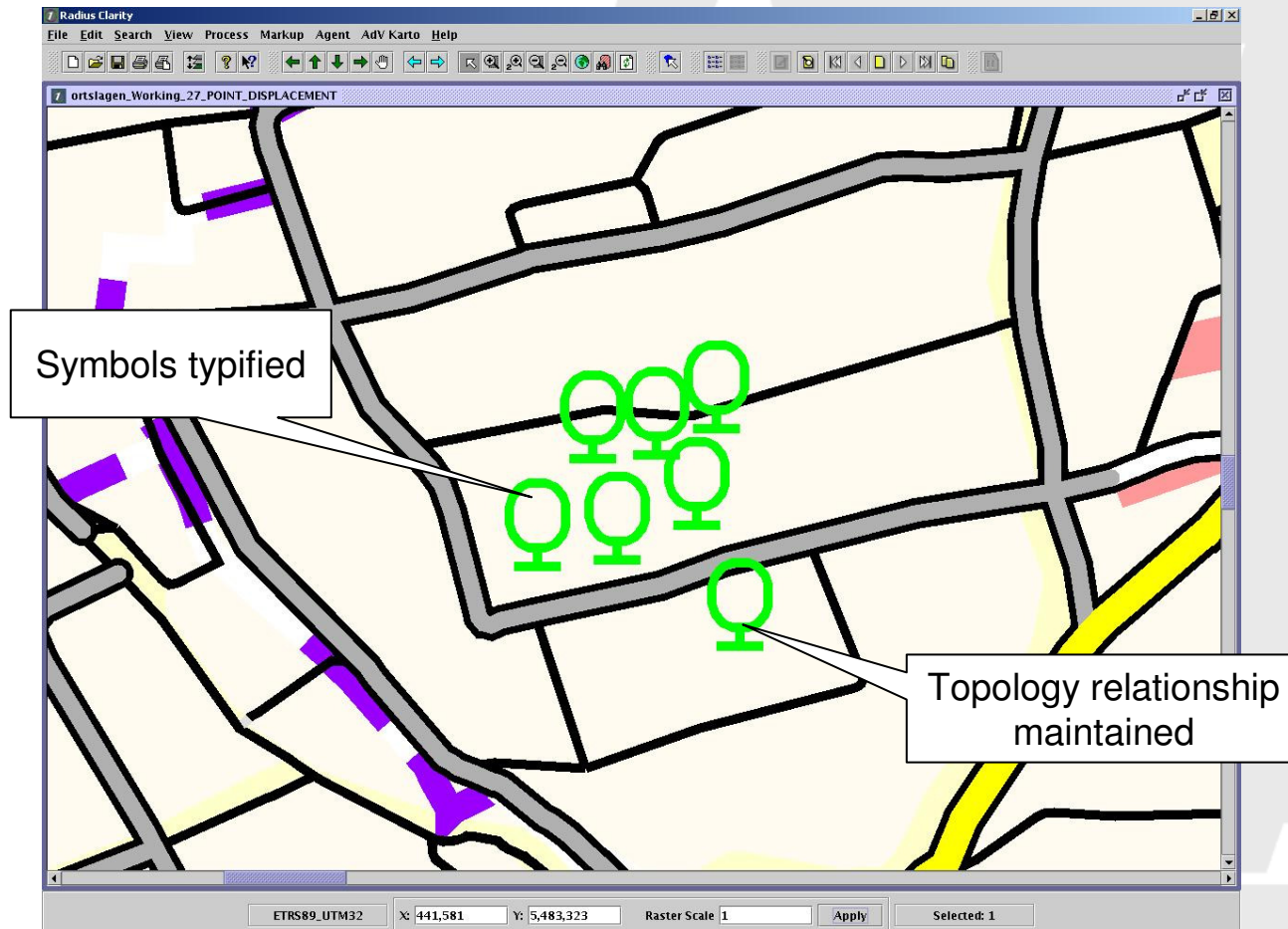
- Point symbols that overlap should be detected and using typification reduced in number for displaying at 1:50,000
- The number of symbols maintained should be determined by Topfer's Radix Law
- The placement of remaining symbols should be representative of original placement of symbols



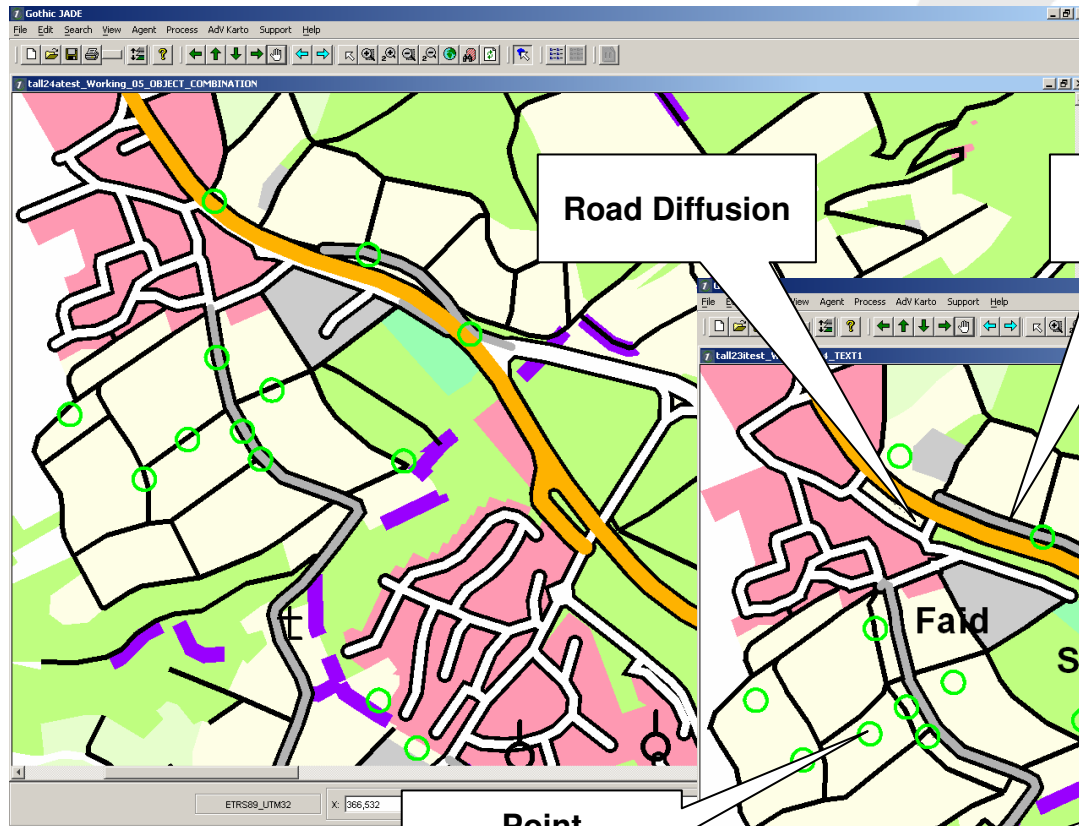
AdV Automatic Generalisation



AdV Automatic Generalisation

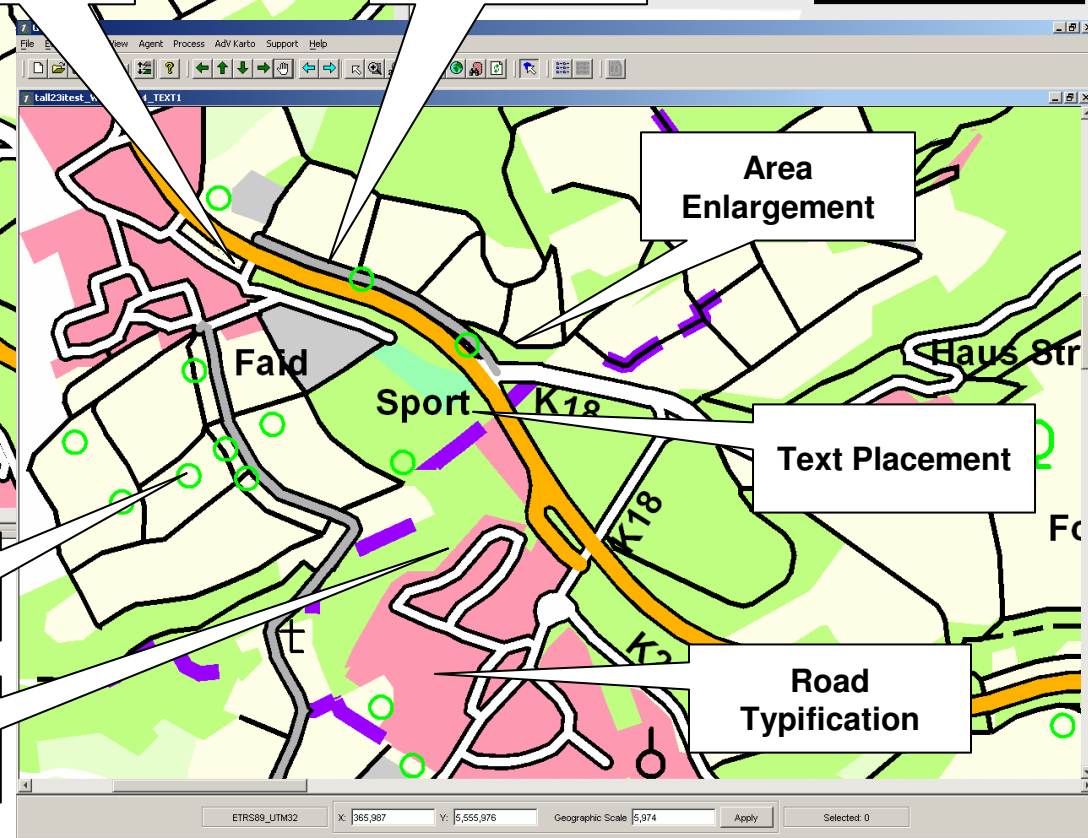


DML50.1



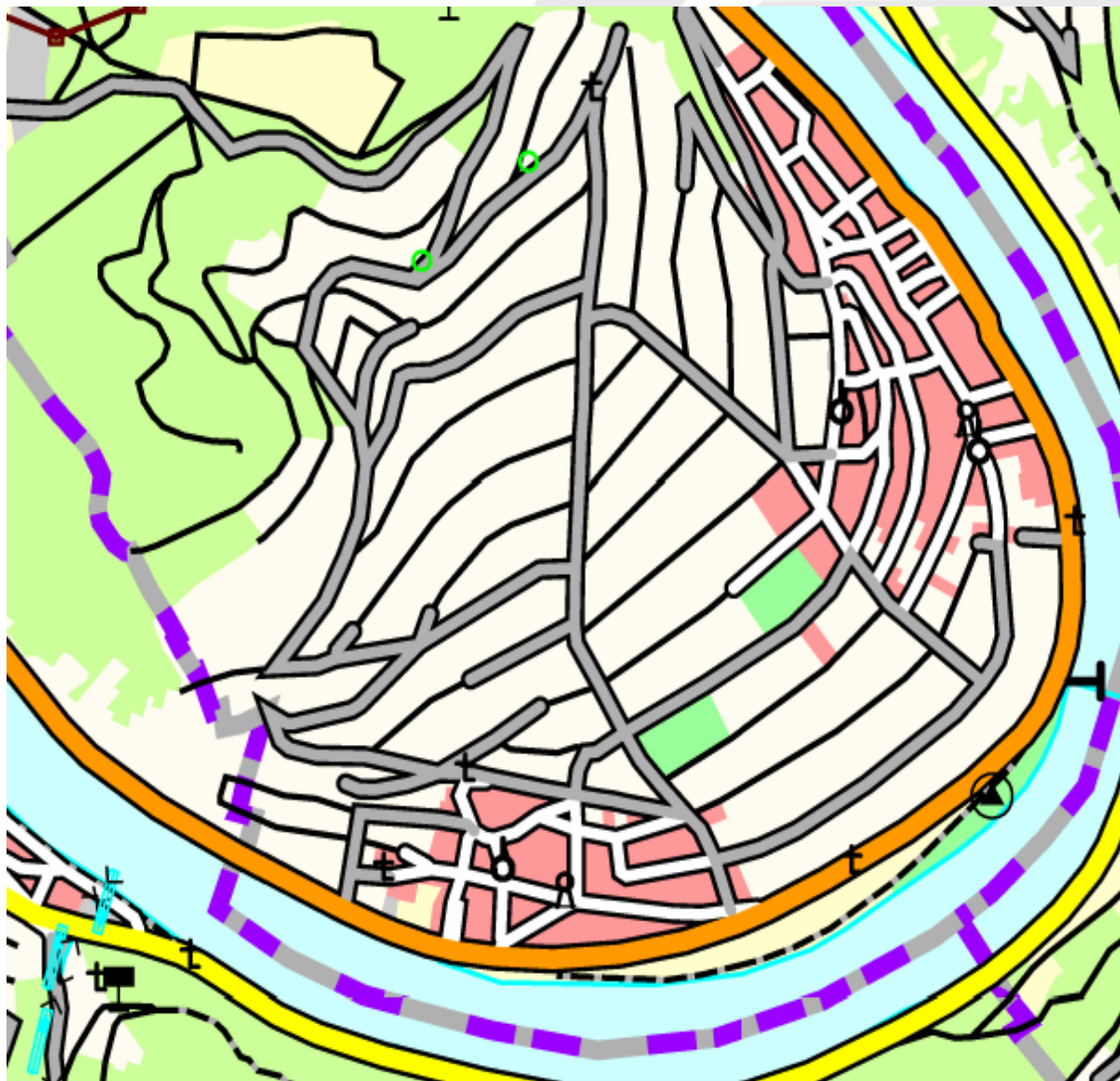
Share Casing

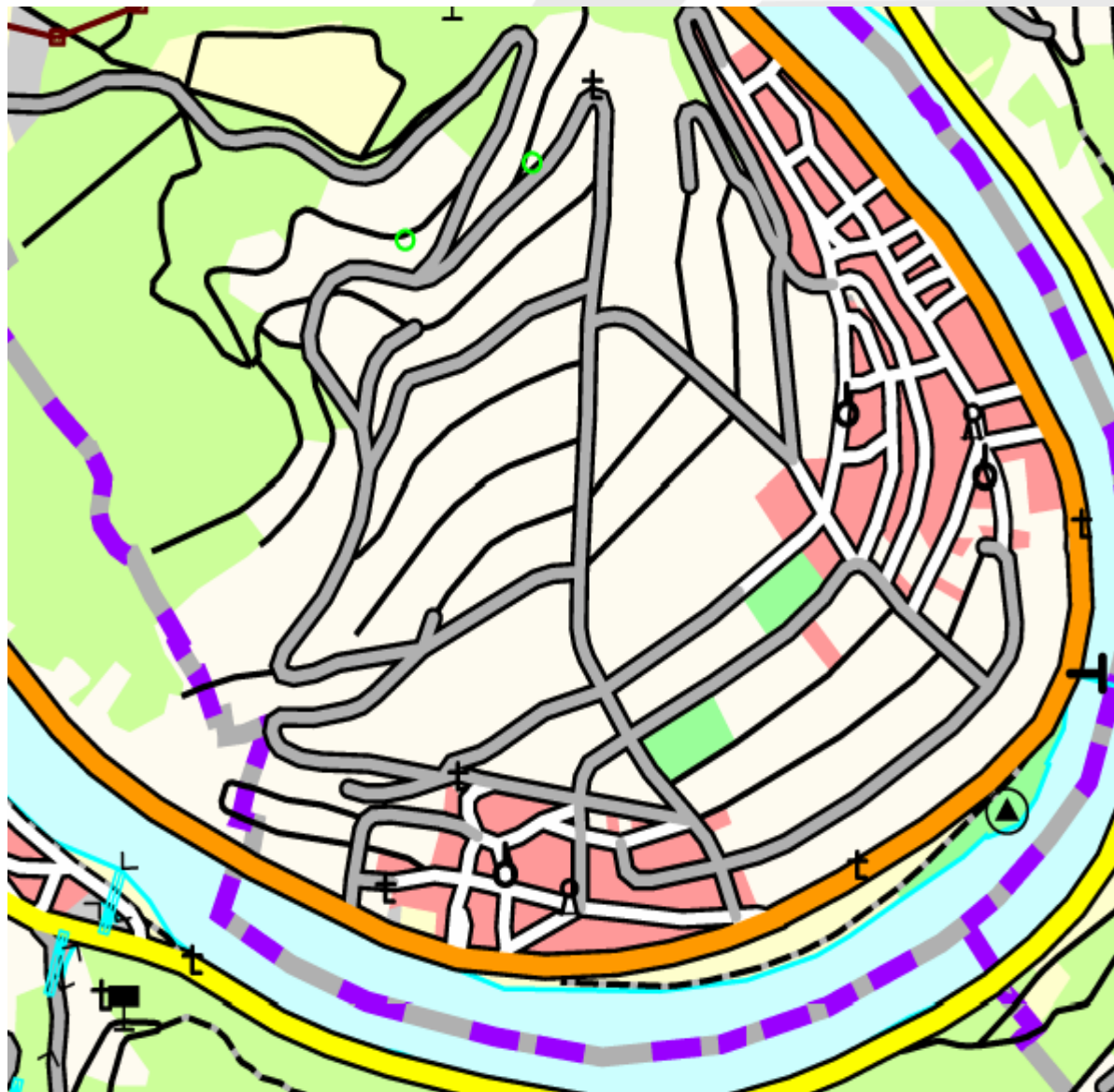
DML50.2



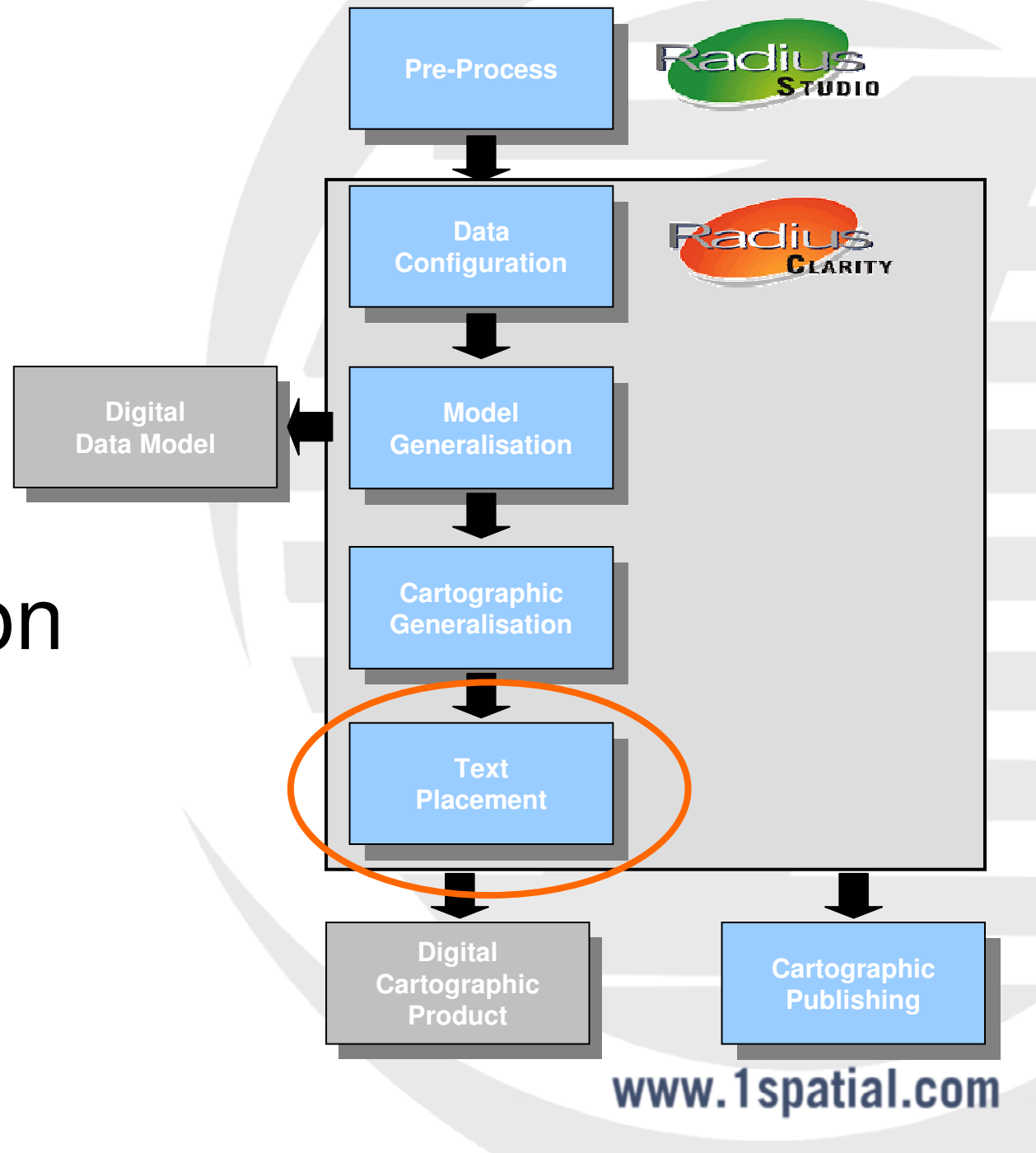
Point Displacement

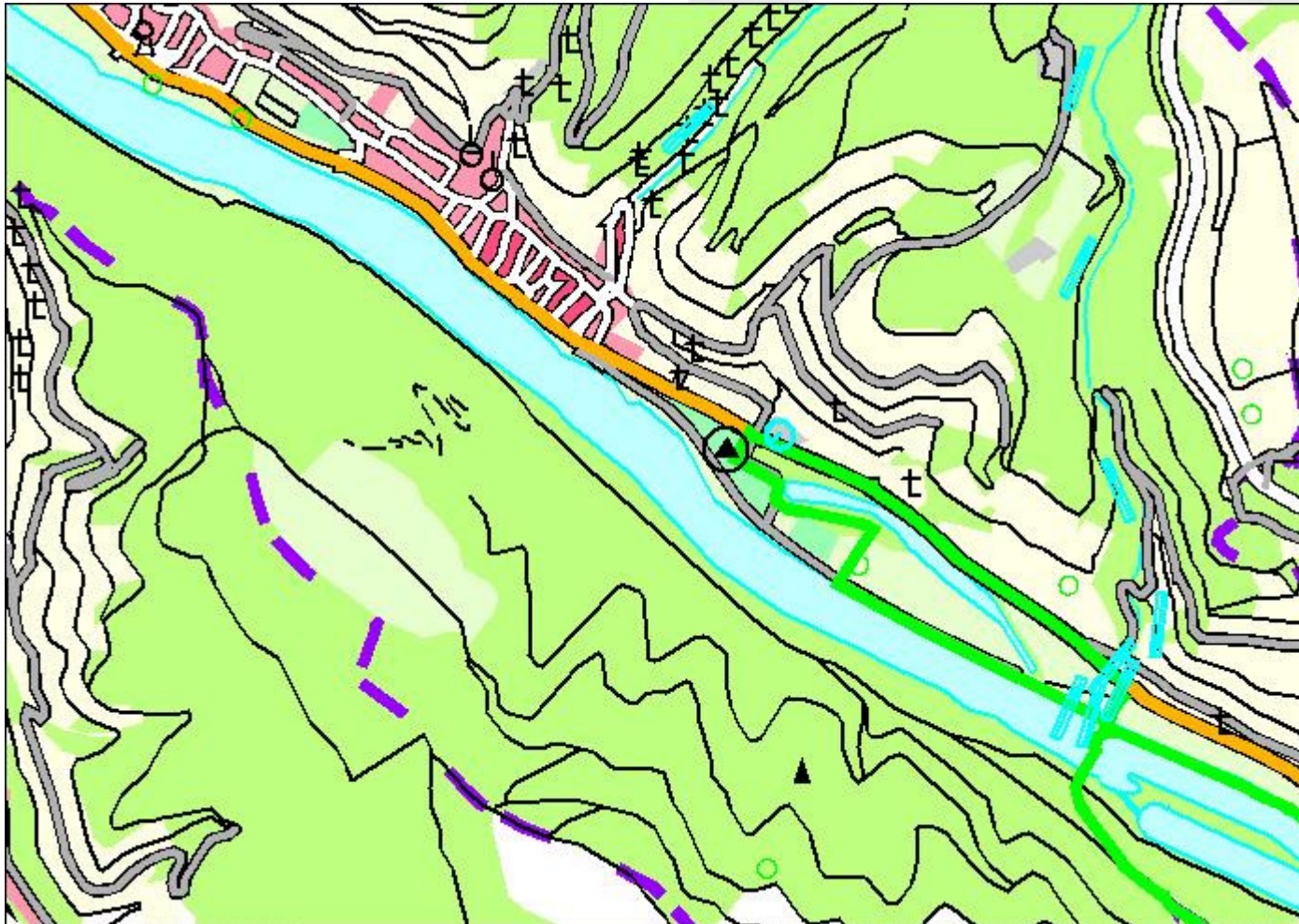
Simplification of Areas (Visvalingham)





Automatic Generalisation Workflow

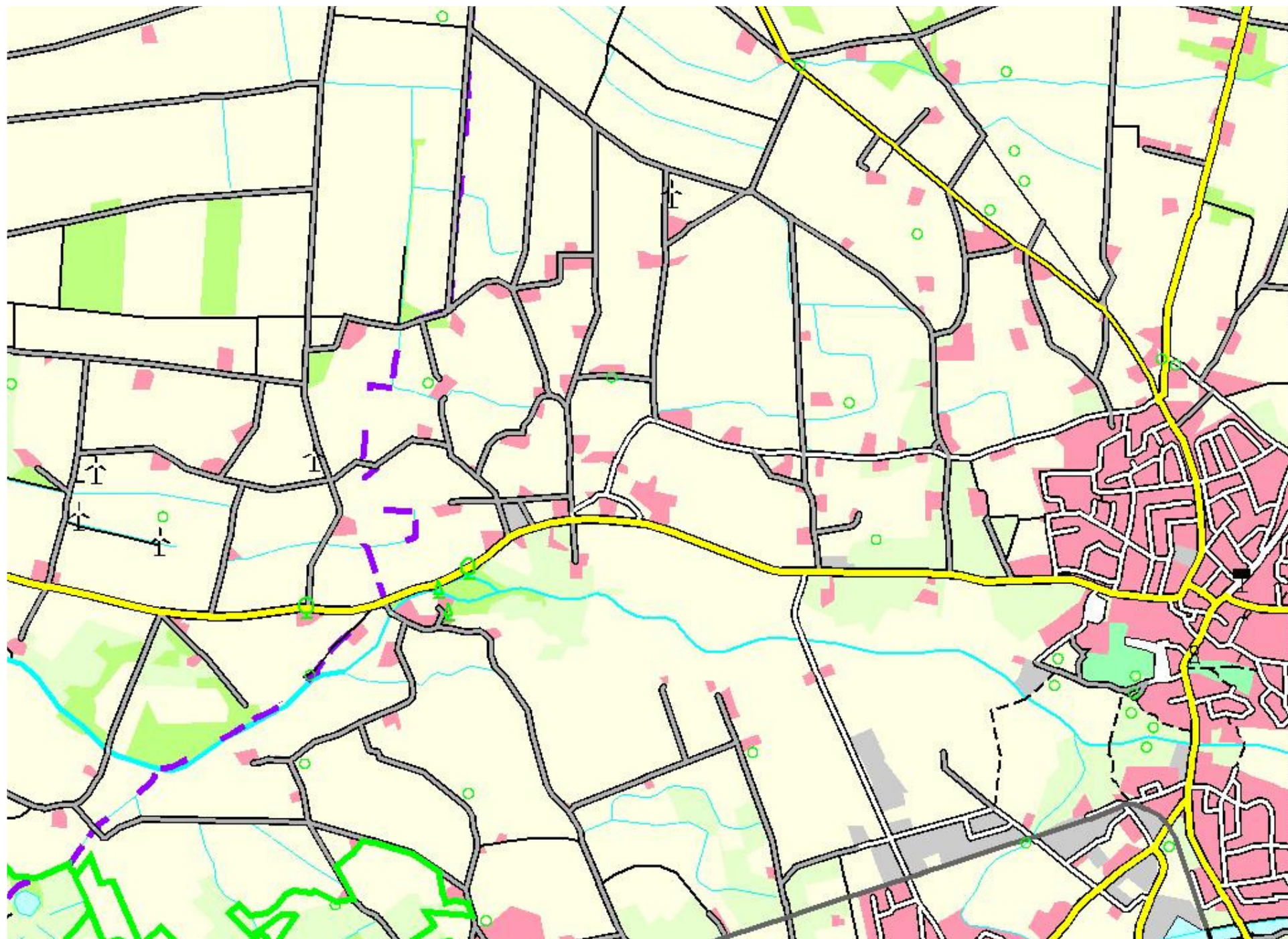


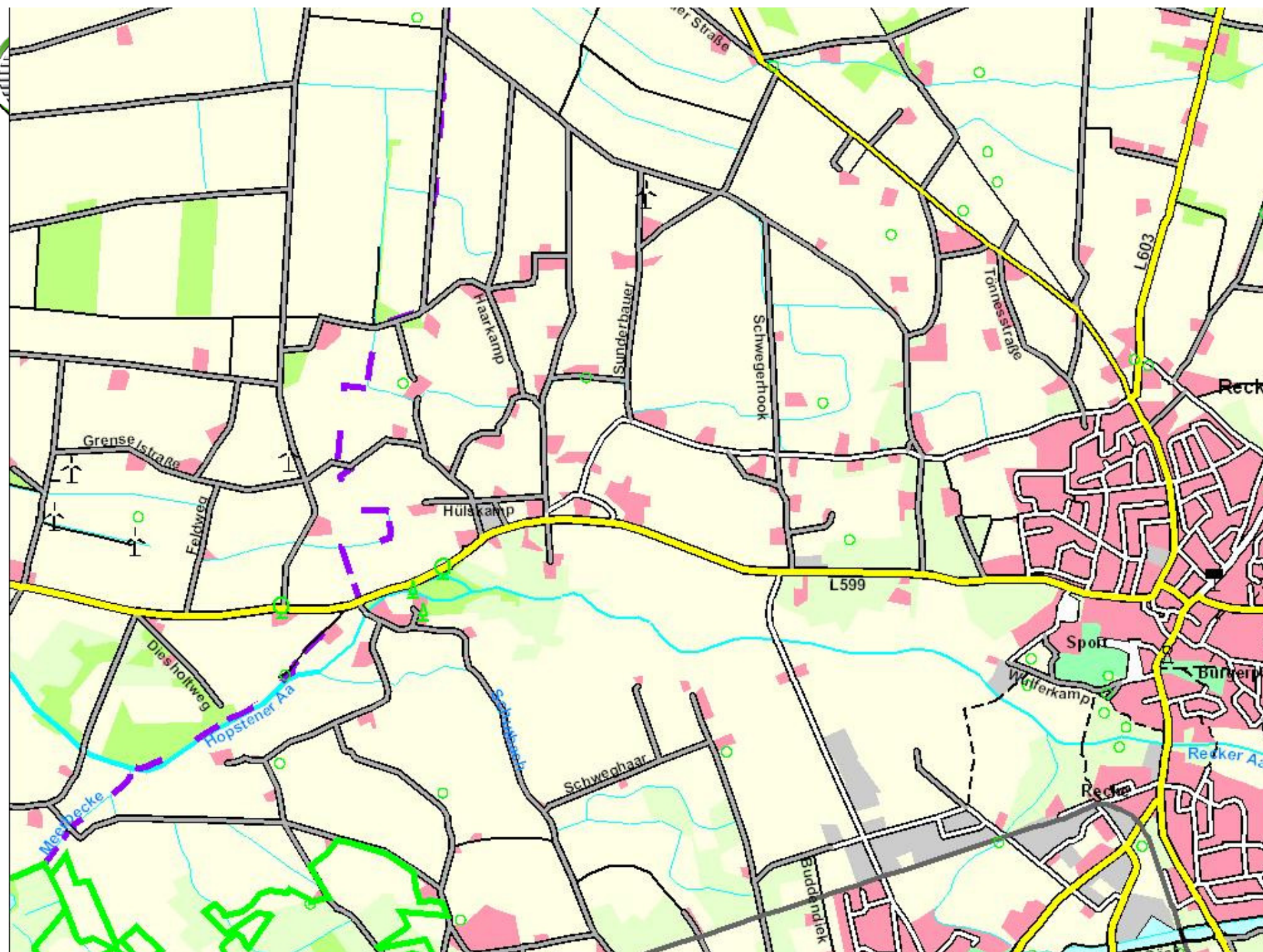












Futures

- Deliver AdV Karto - June 08
 - 30 new algorithms
 - Integrate Radius ClearText with Radius Clarity
 - Implement Region Based Processing
- Clarity 2.7 - Q4 2008
 - Consolidation of functionality
 - IGN France: 1:25K->1:50K
 - MAGNET

ROADMAP

- Extend Model Capabilities in Radius Clarity
- Extended algorithms for further scales
- Web Services

